

Constructive algorithm for path-width of matroids

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joint work with

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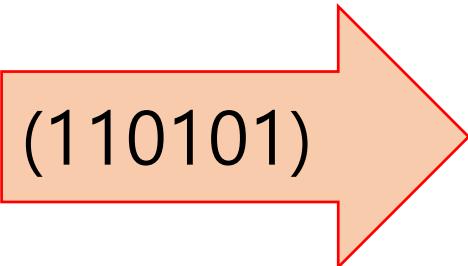
Consider the linear code C that is generated by (100001) , (010100) , and (001010) .

$\{(000000), (100001), (010100), (001010), (110101), (101011), (011110), (111111)\}$

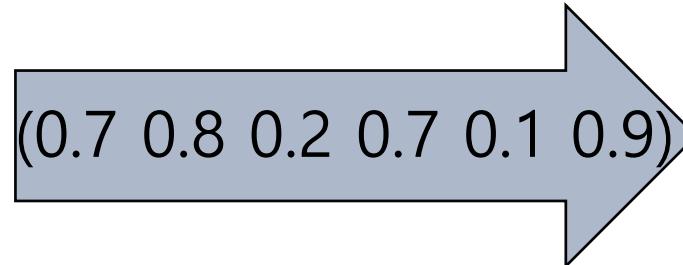
The generator matrix is $\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{pmatrix}$.



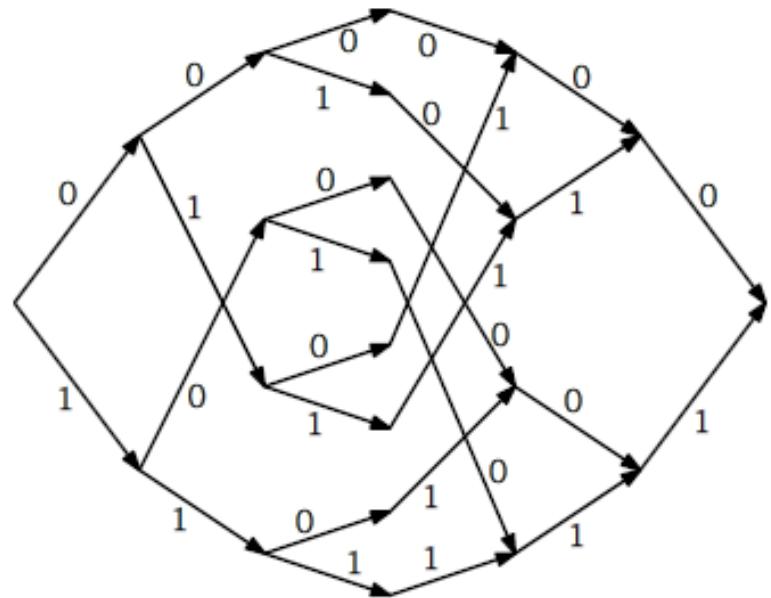
(110101)



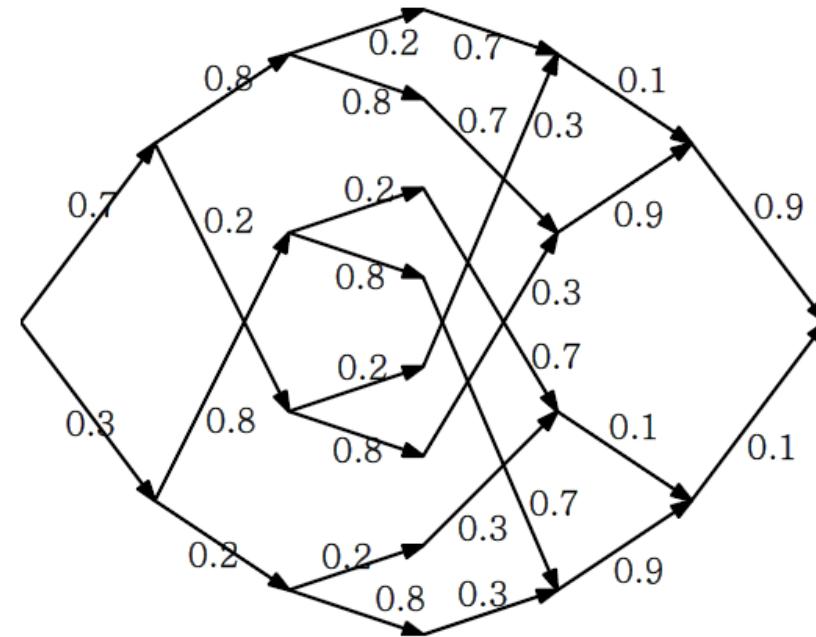
$(0.7 \ 0.8 \ 0.2 \ 0.7 \ 0.1 \ 0.9)$



$\{(000000), (100001), (010100), (001010), (110101), (101011), (011110), (111111)\}$

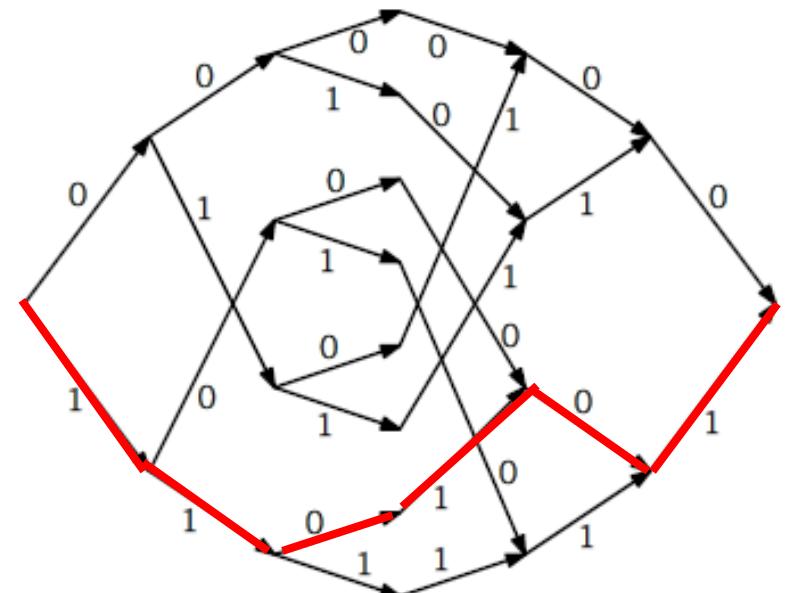


trellis

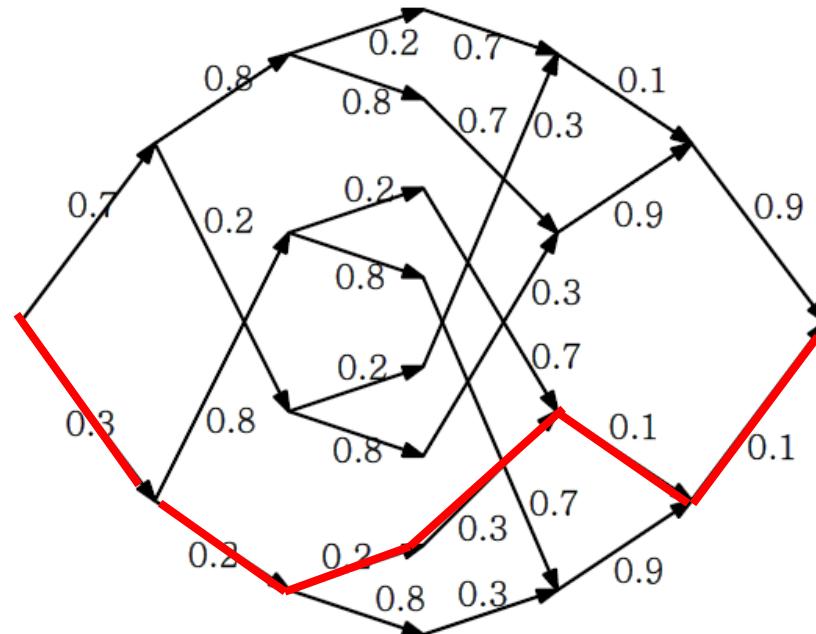


(0.7 0.8 0.2 0.7 0.1 0.9)

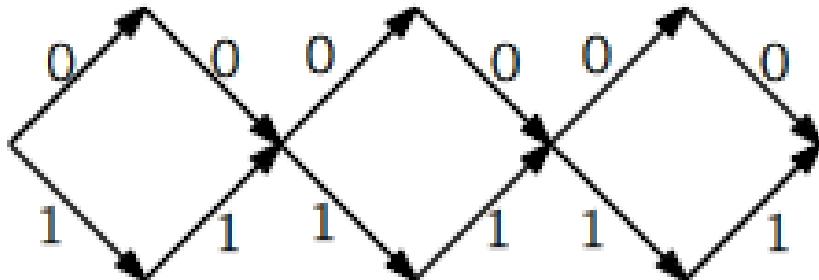
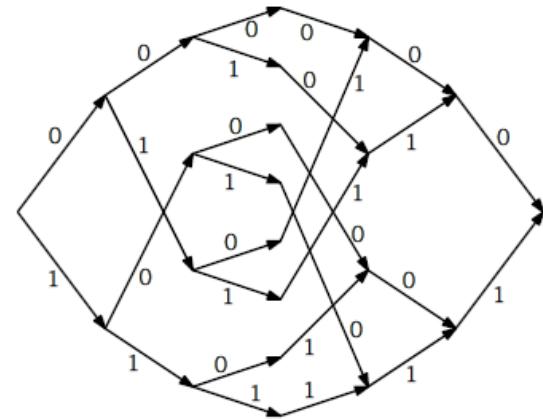
$\{(000000), (100001), (010100), (001010), (110101), (101011), (011110), (111111)\}$



(110101)



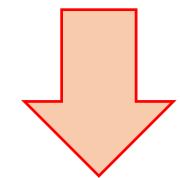
$\{(000000), (100001), (010100), (001010), (110101), (101011), (011110), (111111)\}$



Want to make better trellis

Permute the columns of

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{pmatrix}$$



$$\pi = (1)(4)(5)(2,3,6)$$

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

Use (0.7 0.9 0.8 0.7 0.1 0.2) instead of (0.7 0.8 0.2 0.7 0.1 0.9)

Definition (Path-width)

A **set V of n vectors** over a finite field F has *path-width at most k* if there exists a **permutation v_1, v_2, \dots, v_n** of V satisfying that for all i
 $\dim\langle v_1, v_2, \dots, v_i \rangle \cap \langle v_{i+1}, v_{i+2}, \dots, v_n \rangle \leq k.$

Note that such permutation is called a *linear layout of path-width $\leq k$* .

$$\begin{array}{ccc|ccc} v_1 & v_2 & v_3 & v_4 & v_5 & v_6 \\ \hline 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{array}$$

3

$$\begin{array}{ccc|ccc} v_1 & v_6 & v_2 & v_4 & v_5 & v_3 \\ \hline 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{array}$$

1

Note that since we only consider '*F*-representable matroids' with a fixed finite field *F*, we can say that a **F-representable matroid** is a **set of vectors** over *F*.

Path-width Problem

Input : a set V of **n vectors** over F

Parameter : a nonnegative integer k

Output : a **linear layout** v_1, v_2, \dots, v_n of V satisfying that for all i

$$\dim\langle v_1, v_2, \dots, v_i \rangle \cap \langle v_{i+1}, v_{i+2}, \dots, v_n \rangle \leq k$$

if it exists.

Path-width Problem (decision version)

Input : a set V of **n vectors** over F

Parameter : a nonnegative integer k

Output : **YES** if there exists a **linear layout** v_1, v_2, \dots, v_n of V satisfying that for all i

$$\dim\langle v_1, v_2, \dots, v_i \rangle \cap \langle v_{i+1}, v_{i+2}, \dots, v_n \rangle \leq k$$

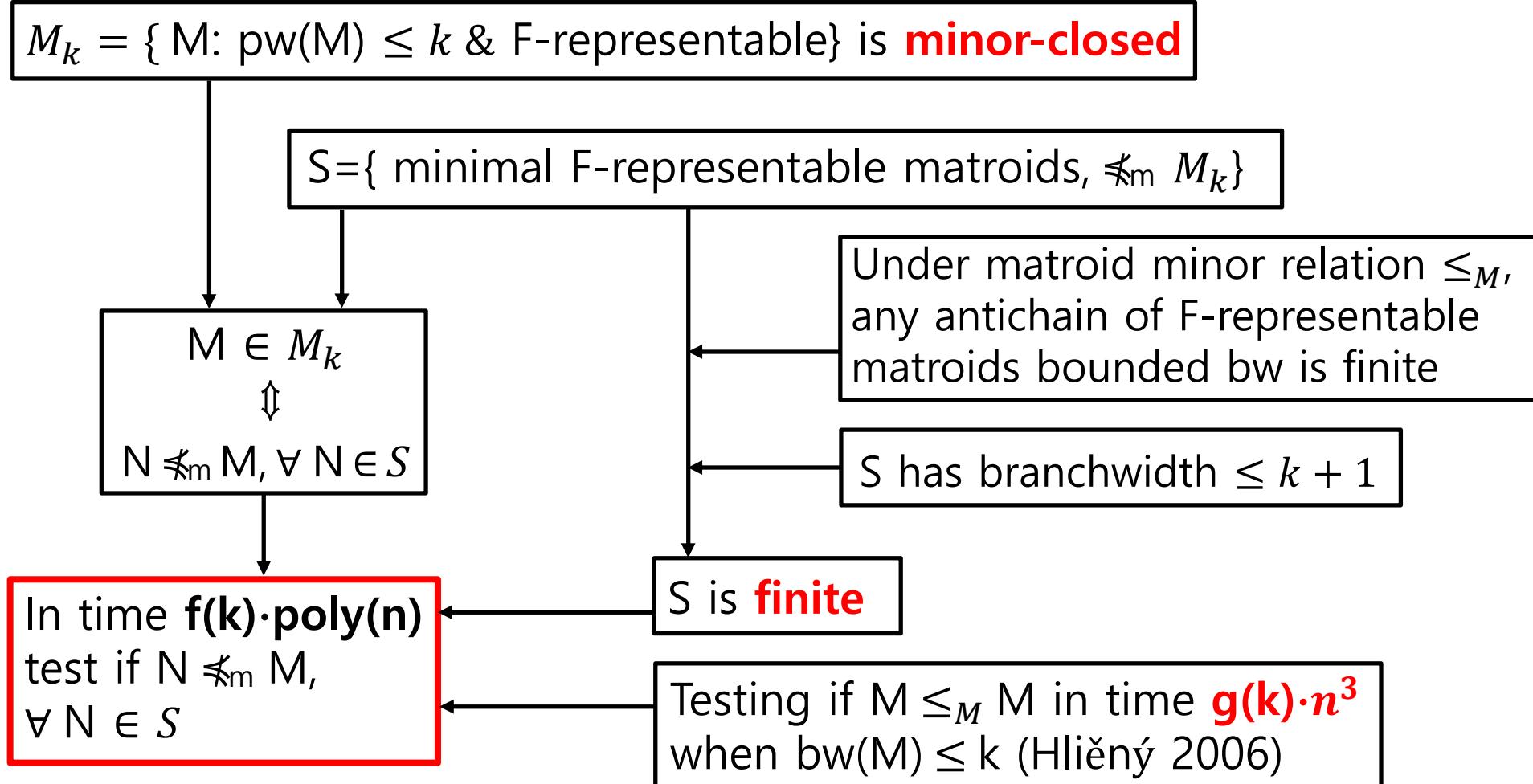
NO otherwise.

Note that this problem is NP-complete [Kashyap 2008].

Our algorithm is **FPT** algorithm.

Roughly speaking, we say **FPT** if the time complexity is $f(k) \cdot \text{poly}(n)$.

Decision FPT algorithm for an F-representable matroid path-width $\leq k$



Our results

Constructive algorithm for path-width of n subspaces

Input : n subspaces

Output : a linear layout of path-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

$$V_1, V_2, \dots, V_n$$

where $V_i = \text{span}(v_1, v_2, \dots, v_j)$

Constructive algorithm for path-width of n vectors

Input : n vectors

Output : a linear layout of path-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

$$v_1, v_2, \dots, v_n$$

Our results

Constructive algorithm for trellis-width of linear codes

Input : linear code
Output : a linear layout of trellis-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$

Linear code whose generator matrix is

$$(v_1 \ v_2 \ \cdots \ v_n)$$

Constructive algorithm for path-width of n subspaces

Input : n subspaces
Output : a linear layout of path-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$

V_1, V_2, \dots, V_n
where $V_i = \text{span}(v_1, v_2, \dots, v_j)$

Constructive algorithm for path-width of matroids

Input : matroid (F-representable)
Output : a linear layout of path-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$

Matroid represented by
 v_1, v_2, \dots, v_n

Our results

Constructive algorithm for trellis-width of linear codes

Input : linear code
Output : a linear layout of trellis-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$

Constructive algorithm for path-width of n subspaces

Input : n subspaces
Output : a linear layout of path-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$

Constructive algorithm for path-width of matroids

Input : matroid (F-representable)
Output : a linear layout of path-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$



Constructive algorithm for linear rank-width of graphs

Input : graph
Output : a linear layout of linear rank-width $\leq k$ if it exists
Time : $f(k) \cdot n^3$

Rank-width is a width-parameter introduced by Oum and Seymour, which is equivalent to **clique-width**.

Our results

Constructive algorithm for path-width of n subspaces

Input : n subspaces

Output : a linear layout of path-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

Constructive algorithm for trellis-width of linear codes

Input : linear code

Output : a linear layout of trellis-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

Constructive algorithm for path-width of matroids

Input : matroid (F-representable)

Output : a linear layout of path-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

Constructive algorithm for linear rank-width of graphs

Input : graph

Output : a linear layout of linear rank-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

Exact algorithm for path-width of matroids

Input : matroid (F-representable, bounded branch-width)

Output : path-width of given matroid

Time : $\text{poly}(n)$

Exact algorithm for linear rank-width of graphs

Input : graph of bounded rw

Output : linear rank-width of given graph

Time : $\text{poly}(n)$

Approximation algorithm for linear clique-width of graphs

Input : graph

Output : linear $(2^k + 1)$ -expression of given graph

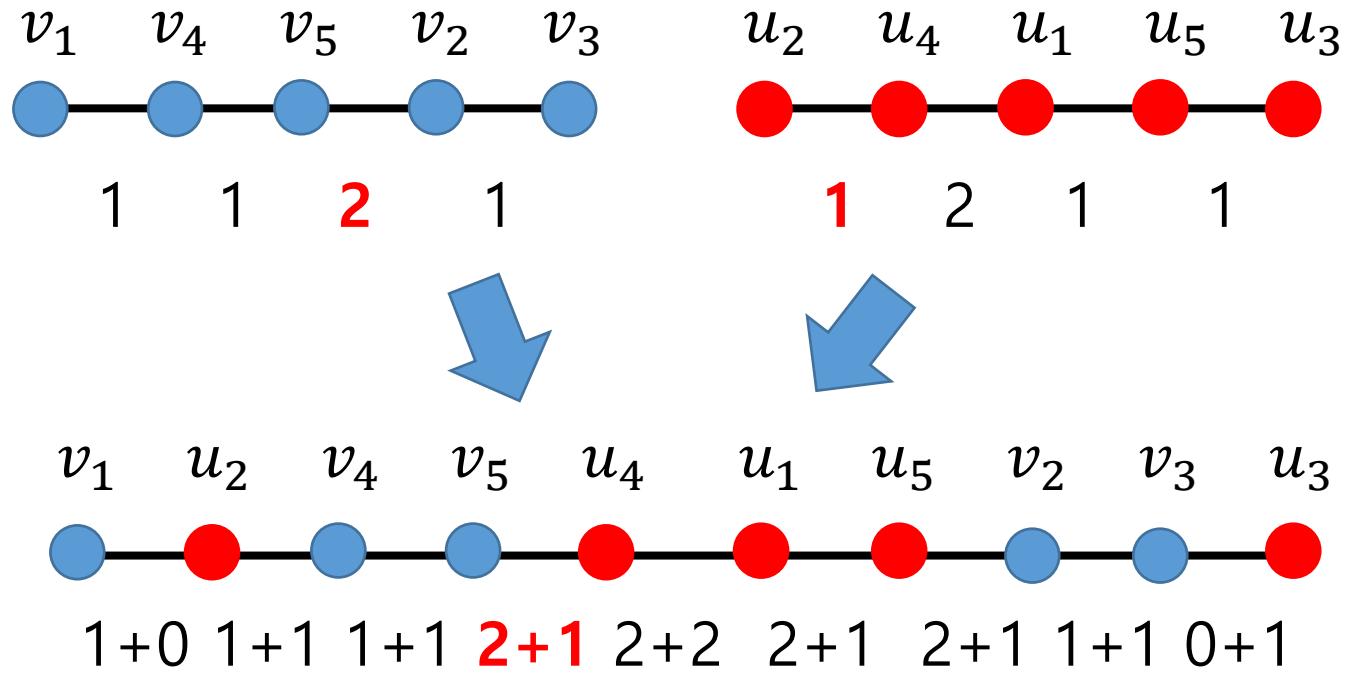
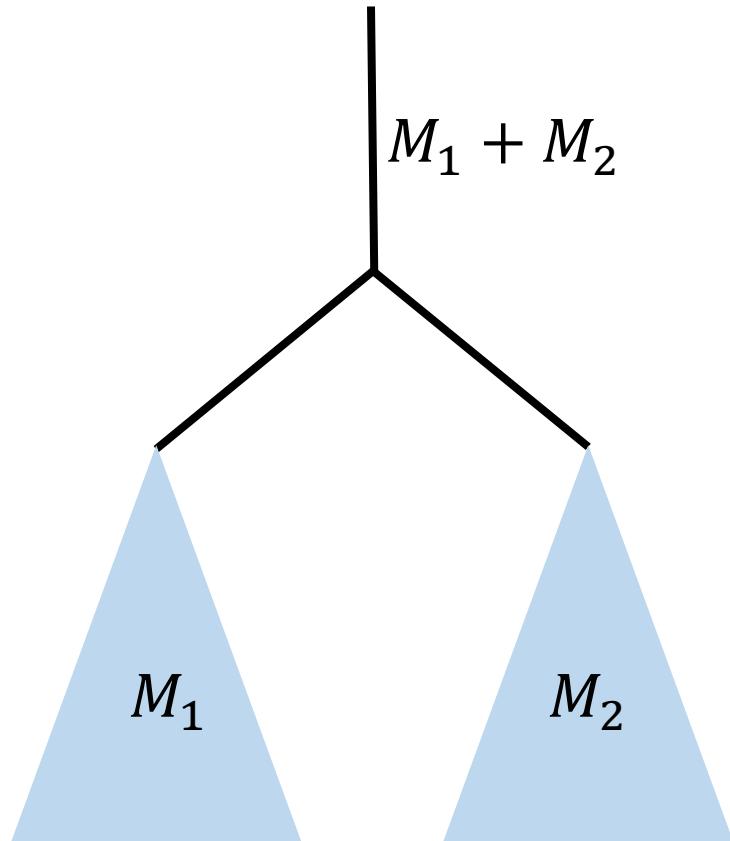
Time : $f(k) \cdot n^3$

Proof ideas

1. Dynamic programming
2. Typical sequence
3. Subspace analysis (linear algebra)

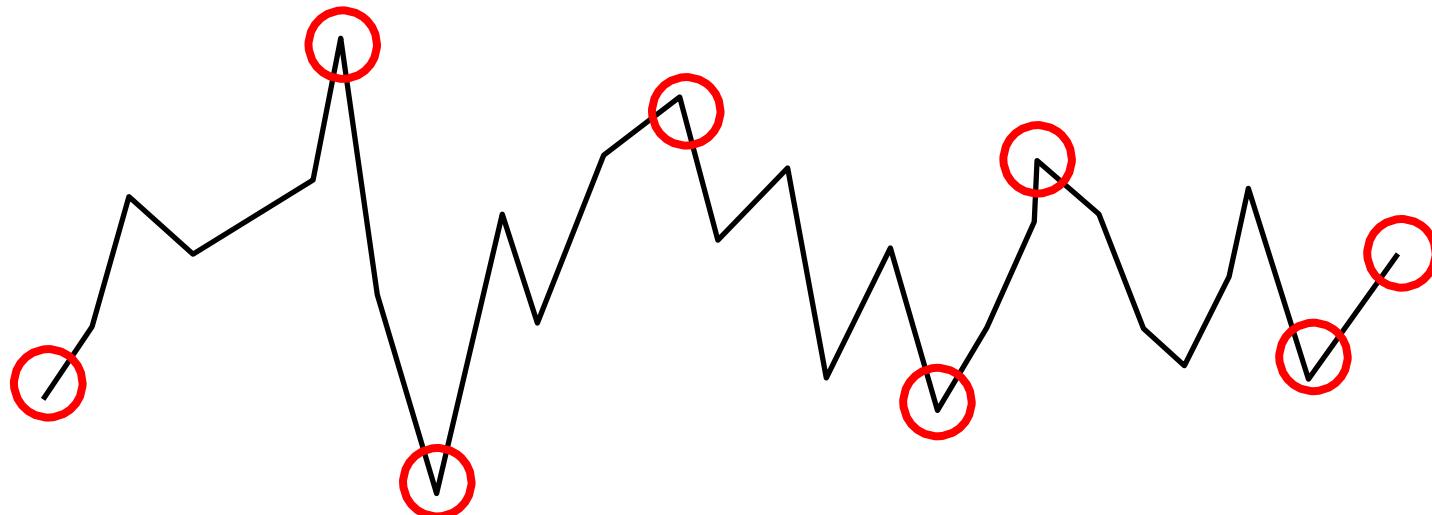
Proof ideas

1. Dynamic programming



Proof ideas

2. Typical sequence



3 6 9 0 5 4 8 5 6 2

3 9 0 5 4 8 5 6 2

3 9 0 8 5 6 2

3 9 0 8 2

Constructive algorithm for path-width of n subspaces

Input : n subspaces

Output : a linear layout of path-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

Constructive algorithm for path-width of matroids

Input : matroid (F-representable)

Output : a linear layout of path-width $\leq k$ if it exists

Time : $f(k) \cdot n^3$

Further questions

1. FPT algorithms for path-width of general matroids
2. Can $O(n^3)$ factor in the running time improved?
e.g. $O(n^w)$ (w =matrix multiplication exponent)