

Talk about “Burq, N., Gérard, P., and Tzvetkov, N., Two singular dynamics of the nonlinear Schrödinger equation on a plane domain, Geometric And Functional Analysis, 13(1), 1-19”.

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1 introduction

In this talk, we study “Burq, N., Gérard, P., and Tzvetkov, N., Two singular dynamics of the nonlinear Schrödinger equation on a plane domain, Geometric And Functional Analysis, 13(1), 1-19.”.

We consider the following the cubic, focusing nonlinear Schrödinger equation (NLS), posed on Ω

$$(NLS) \quad (i\partial_t + \Delta)u = -|u|^2u, \quad \text{in } \mathbb{R} \times \Omega$$

with initial data

$$u(0, x) = u_0(x), \quad x \in \Omega,$$

and Dirichlet boundary conditions

$$u(t, x) = 0 \quad (t, x) \in \mathbb{R} \times \partial\Omega,$$

where Ω is a domain of \mathbb{R}^2 .

First, we define the local well-posedness in $H^s(\Omega)$ with uniformly continuous flow map for data in any ball of $H^s(\Omega)$.

Definition 1.1. (see [5, 9]) We say that the Cauchy problem (NLS) is locally well-posed in $H^s(\Omega)$ with uniformly continuous flow map for data in any ball of $H^s(\Omega)$ if for any $R > 0$ there exist $T > 0$ and a functional space X_T continuously embedded in $C([-T, T], H^s(\Omega))$ such that for every

$$u_0 \in B_R := \{u_0 \in H^s(\Omega) : \|u_0\|_{H^s} < R\}$$

the Cauchy problem (NLS) has a unique solution $u \in X_T$. Moreover

1. The map $u_0 \rightarrow u$ is uniformly continuous from B_R to $C([-T, T], H^s(\Omega))$.
2. If $u_0 \in H^1(\Omega)$, $u \in C([-T, T], H^1(\Omega))$ and satisfies the usual conservation laws

$$\begin{aligned} \|u(t)\|_{L^2} &= \|u_0\|_{L^2}, \\ \|\nabla u(t)\|_{L^2}^2 - \frac{1}{2}\|u(t)\|_{L^4}^4 &= \text{const.} \end{aligned}$$

Next, we define the ground state Q on \mathbb{R}^2 as the unique positive radial solution of

$$(-\Delta_{\mathbb{R}^2} + 1)Q = |Q|^2Q \quad \text{in } \mathbb{R}^2,$$

(see [1, 10].)

2 Known results

1. the case of $\Omega = \mathbb{R}^2$

- (a) If $s > 0$, then (NLS) is locally well-posed in $H^s(\mathbb{R}^2)$ with uniformly continuous flow map for data in any ball of $H^s(\mathbb{R}^2)$ (see Cazenave-Weissler [7]).
- (b) (NLS) is globally well-posed for initial data with L^2 norm smaller than the L^2 norm of the ground state Q (see Weinstein [12].)
- (c) If $\|\varphi\|_{L^2} = \|Q\|_{L^2}$ and the solution u with $u(0) = \varphi$ is blow-up in finite time $T > 0$, then there exist $\theta \in \mathbb{R}$, $\omega > 0$, $x_0 \in \mathbb{R}^2$ and $x_1 \in \mathbb{R}^2$ such that for $t < T$

$$u(t, x) = \frac{\omega}{T-t} e^{i\theta + i|x-x_0|^2/4(t-T) - i\omega^2/(t-T)} Q\left(\frac{\omega}{T-t}(x-x_0) - x_1\right),$$

$$\text{and } \|\nabla u(t, \cdot)\|_{L^2}^2 = \frac{\omega^2}{(T-t)^2} \|\nabla Q\|_{L^2}^2 + \text{Re} \int_{\mathbb{R}^2} \frac{ix}{T-t} \cdot (\nabla Q)Q + \int_{\mathbb{R}^2} \frac{|x|^2}{4\omega^2} Q^2 dx. \text{ (see [11]).}$$

- 2. If $\Omega = \mathbb{T}^2$ or a square and $s > 0$, then (NLS) is locally well-posed in $H^s(\Omega)$ with uniformly continuous flow map for data in any ball of $H^s(\Omega)$ (see Bourgain [3] and Burq-Gérard-Tzvetkov [6]).
- 3. If Ω is a compact 2-dimensional smooth Riemannian manifold with boundary and $s > 1/2$, then (NLS) is locally well-posed in $H^2(\mathbb{R}^2)$ with uniformly continuous flow map for data in any ball of $H^s(\Omega)$ (see Burq-Gérard-Tzvetkov [4] and Blair-Smith-Sogge [2].)
- 4. If $\Omega = S^2$ and $s \in [0, \frac{1}{4}[$, then (NLS) is not locally well-posed in $H^s(\Omega)$ with uniformly continuous flow map for data in any ball of $H^s(\Omega)$ (see Burq-Gérard-Tzvetkov [5].)

3 Main results

We show the following results.

Theorem 3.1. ([6]) *Let Ω be a smooth bounded domain of \mathbb{R}^2 . Let $x_0 \in \Omega$ with $\psi \in C_0^\infty(\Omega)$, $\psi = 1$ in a neighborhood of x_0 . Then there exist $\kappa > 0$, $\lambda_0 > 0$ such that for every $\lambda > \lambda_0$ there exist $T_\lambda > 0$ and a family $\{r_\lambda\}$ of functions define on $[0, T_\lambda[\times \Omega$ satisfying*

$$\|r_\lambda(t, \cdot)\|_{H^2} \leq ce^{-\frac{\kappa}{\lambda(T_\lambda-t)}}, \quad t \in [0, T_\lambda[\quad (3.1)$$

such that

$$u_\lambda(t, x) = \frac{1}{\lambda(T_\lambda-t)} \psi(x) e^{\frac{i(4-\lambda^2(x-x_0)^2)}{4\lambda^2(T_\lambda-t)}} Q\left(\frac{x-x_0}{\lambda(T_\lambda-t)}\right) + r_\lambda(t, x), \quad x \in \Omega, t \in [0, T_\lambda[\quad (3.2)$$

are solutions of (NLS), satisfying the Dirichlet boundary conditions, which blow-up at x_0 in time T_λ in the energy space H^1 with blow up speed $(T_\lambda - t)^{-1}$. Moreover, $\|u_\lambda(t, \cdot)\|_{L^2} = \|Q\|_{L^2}$.

Remark 1. If $u_0 \in H^1(\Omega)$ and $\|u_0\|_{L^2} < \|Q\|_{L^2}$, then the local solution of (NLS) with initial data u_0 can be extended to the whole real line in time t .

Theorem 3.2. ([6]) *Let $D = \{x \in \mathbb{R}^2 : |x| < 1\}$ be the unit disc in \mathbb{R}^2 and Δ_D be the Laplace operator on D with Dirichlet boundary conditions. Fix $\kappa > 0$ and $s \in]1/5, 1/2[$. Then there exists a sequence $\phi_n(x)$ of eigenfunctions of $-\Delta_D$ with corresponding eigenvalues ζ_n ($\lim_{n \rightarrow \infty} \zeta_n = \infty$) such that $\|\phi_n\|_{H^s} \approx 1$ and equation (NLS) with Cauchy data $\kappa\phi_n(x)$, has, for $n \gg 1$, a unique global solution $u_n(t, x)$ which can be represented as*

$$u_n(t, x) = \kappa e^{-it(\zeta_n - \kappa^2 \omega_n)} (\phi_n(x) + r_n(t, x)), \quad (3.3)$$

where $\omega \approx n^{\frac{2}{3}-2s}$ and $r_n(t, x)$ satisfies for any $T > 0$, n large enough and $t \in [0, T]$

$$\|r_n(t, \cdot)\|_{H^s} \leq Cn^{-\delta} \quad (3.4)$$

where $\delta > 0$ and C is independent of n . Moreover, if $0 < \kappa < 1$

$$\|u_n\|_{L^\infty(\mathbb{R}, H^s(D))} \leq C\kappa. \quad (3.5)$$

Remark 2. By Theorem 3.2, the Cauchy problem associated to (NLS) is not locally well-posed in $H^s(D)$ with uniformly continuous flow map for data in any ball of $H^s(D)$ for $s \in]1/5, 1/3[$. Indeed, we fix $s \in]1/5, 1/3[$, $\kappa > 0$ and a sequence $\{\kappa_n\}$ tending to κ . Denote by $u_{\kappa, n}$ (resp. $u_{\kappa_n, n}$) the solution of (NLS) with initial data $\kappa\phi_n$ (resp. $\kappa_n\phi_n$). Then, $\|\kappa\phi_n - \kappa_n\phi_n\|_{H^s} \rightarrow 0$ as $n \rightarrow \infty$. On the other hand,

$$\|u_{\kappa, n}(t, \cdot) - u_{\kappa_n, n}(t, \cdot)\|_{H^s} \geq C|e^{it\omega_n(\kappa^2 - \kappa_n^2)} - 1| - Cn^{-\delta},$$

where $\delta > 0$. Then, if $\kappa_n^2 = \kappa^2 + |\omega_n|^{-1/2}$, then for $n \gg 1$ there exists $c > 0$ such that $\|u_{\kappa, n}(t_n, \cdot) - u_{\kappa_n, n}(t_n, \cdot)\|_{H^s} > c$, where $t_n = \pi/(2\omega_n(\kappa^2 - \kappa_n^2))$. Since $\omega_n \rightarrow \infty$ as $n \rightarrow \infty$, then $t_n \rightarrow 0$ as $n \rightarrow \infty$ and the flow map is not uniformly continuous.

4 Proof of Theorem 3.1

Let $T > 0$ and $\lambda > 0$. We define

$$\tilde{R}_\lambda(t, x) = \frac{1}{\lambda(T-t)} e^{\frac{i(4-\lambda^2)(x-x_0)^2}{4\lambda^2(T-t)}} Q\left(\frac{x-x_0}{\lambda(T-t)}\right), \quad (t, x) \in [0, T[\times \mathbb{R}^2.$$

We set $R_\lambda(t, x) := \psi(x)\tilde{R}_\lambda(t, x)$. Constructing a smooth correction $r_\lambda(t, x)$ and choosing T , we make a solution $R_\lambda(t, x) + r_\lambda(t, x)$ of (NLS) by using the contraction mapping principle. Since $\tilde{R}_\lambda(t, x)$ is a solution of (NLS) on \mathbb{R}^2 , we have

$$(i\partial_t + \Delta)R_\lambda = -\psi|\tilde{R}_\lambda|^2\tilde{R}_\lambda + 2\nabla\psi\nabla\tilde{R}_\lambda + (\Delta\psi)\tilde{R}_\lambda.$$

Then, we look for a solution $v \in C([0, T[, H^2(\Omega) \cap H_0^1(\Omega))$ such that

$$\begin{cases} (i\partial_t + \Delta)v = -|R_\lambda + v|^2(R_\lambda + v) + \psi|\tilde{R}_\lambda|^2\tilde{R}_\lambda - 2\nabla\psi\nabla\tilde{R}_\lambda - (\Delta\psi)\tilde{R}_\lambda, \\ v(t) \rightarrow 0 \text{ as } t \rightarrow T (t < T) \text{ in } H^2(\Omega) \cap H_0^1(\Omega). \end{cases} \quad (4.1)$$

Set

$$-|R_\lambda + v|^2(R_\lambda + v) + \psi|\tilde{R}_\lambda|^2\tilde{R}_\lambda - 2\nabla\psi\nabla\tilde{R}_\lambda - \Delta\psi\tilde{R}_\lambda = Q_0 + Q_1(v) + Q_2(v) + Q_3(v),$$

where

$$\begin{cases} Q_0 = \psi(1 - |\psi|^2)|\tilde{R}_\lambda|^2\tilde{R}_\lambda - 2\nabla\psi\nabla\tilde{R}_\lambda - (\Delta\psi)\tilde{R}_\lambda, \\ Q_1(v) = -R_\lambda^2\bar{v} - 2|R_\lambda|^2v, \\ Q_2(v) = -\bar{R}_\lambda v^2 - 2R_\lambda|v|^2, \\ Q_3(v) = -|v|^2v. \end{cases}$$

Then, since there exists $\delta_0 > 0$ such that $\|e^{\delta_0|\cdot|}Q\|_{W^{\infty, 3}(\mathbb{R}^2)} < \infty$, there exists $C, \delta > 0$ such that

$$\|Q_0(t, \cdot)\|_{H^2(\Omega)} \leq Ce^{-\frac{\delta}{\lambda(T-t)}}. \quad (4.2)$$

Indeed, for example there exists $\varepsilon > 0$ such that

$$\begin{aligned} \left\| \psi(1 - |\psi|^2)|\tilde{R}_\lambda|^2\tilde{R}_\lambda \right\|_{L^2(\Omega)}^2 &\leq \frac{C}{(\lambda(T-t))^6} \int_\varepsilon^\infty r e^{\frac{-6\delta_0 r}{\lambda(T-t)}} dr, \\ &\leq \frac{C}{(\lambda(T-t))^5} e^{\frac{-3\delta_0 \varepsilon}{\lambda(T-t)}}, \\ &\leq Ce^{\frac{-\delta_0 \varepsilon}{\lambda(T-t)}}. \end{aligned}$$

Here we used that for $c, \varepsilon > 0$

$$|x|e^{-|cx|} \leq C_{c,\varepsilon} e^{-\frac{|cx|}{1+\varepsilon}}, \quad (4.3)$$

where $C_{c,\varepsilon}$ is independent of x . We look for solutions of (4.1) in the space

$$X_T = \{v \in C([0, T[, H^2(\Omega) \cap H_0^1(\Omega)) : \|v\|_{X_T} < \infty\}$$

where

$$\|v\|_{X_T} = \sup_{t \in [0, T[} \{e^{\frac{\delta}{2\lambda(T-t)}} \|v(t)\|_{L^2(\Omega)} + e^{\frac{\delta}{3\lambda(T-t)}} \|v(t)\|_{H^2(\Omega)}\}.$$

We define

$$\Phi(v)(t) = \int_t^T S(t-\tau)Q_0(\tau)d\tau + \sum_{j=1}^3 \int_t^T S(t-\tau)Q_j(v(\tau))d\tau,$$

$$I_0(t) = \int_t^T S(t-\tau)Q_0(\tau)d\tau,$$

and for $j = 1, 2, 3$

$$I_j(v)(t) = \int_t^T S(t-\tau)Q_j(v(\tau))d\tau,$$

where $S(t)$ is the unitary group which defines the free evolution of the Schrödinger equation on Ω with Dirichlet boundary conditions. Then, we estimate $\|I_j\|_{X_T}$ for $j = 0, 1, 2, 3$ and $\|I_j(v) - I_j(w)\|$ for $j = 1, 2, 3$.

Estimate for I_0 . By the estimate of the source term (4.2),

$$\|I_0\|_{X_T} \leq CT. \quad (4.4)$$

Estimate for $I_1(v)$. Recall $Q_1(v) = -R_\lambda^2 \bar{v} - 2|R_\lambda|^2 v$. For $t \in [0, T[$

$$\begin{aligned} \|I_1(v)(t)\|_{L^2} &\leq C \int_t^T \|R_\lambda(\tau)\|_{L^\infty}^2 \|v(\tau)\|_{L^2} d\tau, \\ &\leq C \|v\|_{X_T} \int_t^T \frac{1}{(\lambda(T-\tau))^2} e^{-\frac{\delta}{2\lambda(T-\tau)}} d\tau, \\ &\leq C \frac{\|v\|_{X_T}}{\lambda^2} \frac{2\lambda}{\delta} e^{-\frac{\delta}{2\lambda(T-t)}} = \frac{C}{\lambda} e^{-\frac{\delta}{2\lambda(T-t)}} \|v\|_{X_T}. \end{aligned}$$

For $t \in [0, T[$

$$\begin{aligned} \|I_1(v)(t)\|_{H^2} &\leq C \int_t^T \|\nabla^2 Q_1(v(\tau))\|_{L^2} d\tau + C \|I_1(t)\|_{L^2}, \\ &\leq C \int_t^T \|\nabla^2 (R_\lambda^2)(\tau)\|_{L^\infty} \|v(\tau)\|_{L^2} d\tau \\ &\quad + C \int_t^T \|\nabla (R_\lambda^2)(\tau)\|_{L^\infty} \|\nabla v(\tau)\|_{L^2} d\tau \\ &\quad + C \int_t^T \|(R_\lambda^2)(\tau)\|_{L^\infty} \|\nabla^2 v(\tau)\|_{L^2} d\tau + \frac{C}{\lambda} e^{-\frac{\delta}{2\lambda(T-t)}} \|v\|_{X_T}. \end{aligned}$$

Since

$$\nabla \tilde{R}_\lambda(\tau, x) = \frac{-i(x-x_0)}{2(T-\tau)} \tilde{R}_\lambda(\tau, x) + \frac{1}{(\lambda(T-\tau))^2} e^{\frac{i(4-\lambda^2(x-x_0)^2)}{4\lambda^2(T-\tau)}} (\nabla Q) \left(\frac{x-x_0}{\lambda(T-\tau)} \right),$$

we have

$$\left\| \nabla^k ((R_\lambda)^2(\tau)) \right\|_{L^\infty} \leq \frac{C(1+\lambda^k)}{(\lambda(T-\tau))^{k+2}}, \quad k = 0, 1, 2, \quad \tau \in [0, T[. \quad (4.5)$$

Using the inequalities

$$\|\nabla v(\tau)\|_{L^2} \leq \|\nabla^2 v(\tau)\|_{L^2}^{1/2} \|v(\tau)\|_{L^2}^{1/2},$$

, (4.3) and (4.5), we obtain for $\lambda \geq 1$ and $T \leq 1$,

$$\begin{aligned} \|I_1(v)(t)\|_{H^2} &\leq C\|v\|_{X_T} \left\{ \frac{1}{\lambda} e^{-\frac{\delta}{2\lambda(T-t)}} + \int_t^T \frac{1+\lambda^2}{(\lambda(T-\tau))^4} e^{-\frac{\delta}{2\lambda(T-\tau)}} d\tau \right. \\ &\quad \left. + \int_t^T \frac{1+\lambda}{(\lambda(T-\tau))^3} e^{-\frac{1}{2}\left(\frac{\delta}{2\lambda(T-\tau)} + \frac{\delta}{3\lambda(T-\tau)}\right)} d\tau + \int_t^T \frac{1}{(\lambda(T-\tau))^2} e^{-\frac{\delta}{3\lambda(T-\tau)}} d\tau \right\}, \\ &\leq C\|v\|_{X_T} \left\{ \frac{1}{\lambda} e^{-\frac{\delta}{2\lambda(T-t)}} + \int_t^T \frac{1+\lambda^2}{(\lambda(T-\tau))^2} e^{-\frac{\delta}{3\lambda(T-\tau)}} d\tau \right. \\ &\quad \left. + \int_t^T \frac{1+\lambda}{(\lambda(T-\tau))^2} e^{-\frac{\delta}{3\lambda(T-\tau)}} d\tau + \int_t^T \frac{1}{(\lambda(T-\tau))^2} e^{-\frac{\delta}{3\lambda(T-\tau)}} d\tau \right\} \\ &\leq C \left(\frac{1}{\lambda} + \lambda^2 T \right) e^{-\frac{\delta}{3\lambda(T-t)}} \|v\|_{X_T}. \end{aligned}$$

Therefore,

$$\|I_1(v)\|_{X_T} \leq C \left(\frac{1}{\lambda} + T^{1/2} \right) \|v\|_{X_T}, \quad (4.6)$$

provided $\lambda^2 T^{1/2} \leq 1$, $\lambda \geq 1$.

Estimate for $I_1(v) - I_1(w)$. Similarly, we obtain

$$\|I_1(v) - I_1(w)\|_{X_T} \leq C \left(\frac{1}{\lambda} + T^{1/2} \right) \|v - w\|_{X_T}, \quad (4.7)$$

provided $\lambda^2 T^{1/2} \leq 1$, $\lambda \geq 1$.

Estimate for $I_2(v)$. Recall that $Q_2(v) = -\bar{R}_\lambda^2 - 2R_\lambda|v|^2$. Using the inequality

$$\|R_\lambda(\tau)\|_{H^2} \leq \frac{C(1+\lambda^2)}{(\lambda(T-\tau))^2},$$

and (4.3), we obtain

$$\begin{aligned} \|I_2(v)(t)\|_{H^2} &\leq C \int_t^T \|R_\lambda(\tau)\|_{H^2} \|v(\tau)\|_{H^2}^2 d\tau, \\ &\leq C \left(\int_t^T \frac{1+\lambda^2}{(\lambda(T-\tau))^2} e^{-\frac{2\delta}{3\lambda(T-\tau)}} d\tau \right) \|v\|_{X_T}^2, \\ &\leq CT(1+\lambda^2) e^{-\frac{\delta}{2\lambda(T-t)}} \|v\|_{X_T}^2. \end{aligned}$$

Hence,

$$\|I_2(v)\|_{X_T} \leq CT^{1/2} \|v\|_{X_T}^2, \quad (4.8)$$

provided $\lambda^2 T^{1/2} \leq 1$, $\lambda \geq 1$.

Estimate for $I_2(v) - I_2(w)$. Similarly, we obtain

$$\|I_2(v) - I_2(w)\|_{X_T} \leq CT^{1/2} (\|v\|_{X_T} + \|w\|_{X_T}) \|v - w\|_{X_T}, \quad (4.9)$$

provided $\lambda^2 T^{1/2} \leq 1$, $\lambda \geq 1$.

Estimate for $I_3(v)$. Recall that $Q_3(v) = -|v|^2v$. We obtain

$$\begin{aligned} \|I_3(t)\|_{H^2} &\leq C \int_t^T \|v(\tau)\|_{H^2}^3 d\tau, \\ &\leq \|v\|_{X_T}^3 \int_t^T e^{-\lambda(T-\tau)} d\tau, \\ &\leq CT e^{-\frac{\delta}{3\lambda(T-t)}} \|v\|_{X_T}^3. \end{aligned}$$

Thus,

$$\|I_3(v)\|_{X_T} \leq CT \|v\|_{X_T}^3. \quad (4.10)$$

Estimate for $I_3(v) - I_3(w)$. Similarly, we obtain

$$\|I_3(v) - I_3(w)\|_{X_T} \leq CT (\|v\|_{X_T}^2 + \|w\|_{X_T}^2) \|v - w\|_{X_T}. \quad (4.11)$$

By (4.4)-(4.11), Φ is a contraction map if $\lambda \gg 1$, $T \ll 1$ and $\lambda^2 T^{1/2} \leq 1$. Therefore, there exists $\lambda_0 > 0$ such that for $\lambda > \lambda_0$ there exist $T_\lambda > 0$ and the unique solution r_λ of (4.1) such that

$$\|r_\lambda(t, \cdot)\|_{H^2} \leq ce^{-\frac{\kappa}{\lambda(T_\lambda - t)}}, \quad t \in [0, T_\lambda[$$

and $u_\lambda(t, x) := R_\lambda(t, x) + r_\lambda(t, x)$ is a solution of (NLS). Moreover, for $t_0 \in [0, T_\lambda[$

$$\|u_\lambda(t_0, \cdot)\|_{L^2} = \lim_{t \rightarrow T_\lambda} \|u_\lambda(t, \cdot)\|_{L^2} = \lim_{t \rightarrow T_\lambda} \|R_\lambda(t, \cdot)\|_{L^2} = \|Q\|_{L^2}.$$

5 Proof of Theorem 2

The Bessel function of order n is defined as follows

$$J_n(z) = \left(\frac{z}{2}\right)^n \sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{z}{2}\right)^{2k}}{k!(n+k)!}.$$

Let $z_{n1} < z_{n2} < z_{n3} < \dots$ be the sequence of the positive zeros of $J_n(z)$. In the following lemma, we get the order of a positive zero of $J_n(z)$.

Lemma 5.1. *Let $n \geq 1$. Then there exists a constant α , independent of n , such that $z_{n1} = n + \alpha n^{1/3} + O(n^\lambda)$, for any $\lambda > 1/6$. Moreover $z_{n2} - z_{n1} \geq Cn^{1/3}$.*

In this talk, we do not prove this lemma (see [6, 8].)

We consider the equation (NLS) on $\Omega = D := \{x \in \mathbb{R}^2 : |x| < 1\}$. By introducing polar coordinates $x_1 = r \cos \theta$, $x_2 = r \sin \theta$, we can get that $f_{nk}(r, \theta) := J_n(z_{nk}r)e^{in\theta}$ is an orthogonal basis of $L^2(D)$ of eigenfunctions for $-\Delta_D$ with corresponding eigenvalue z_{nk}^2 . Then for $s \in [0, 1/2[$ and $u \in L^2(D)$, there exists $c_{nk} \in \mathbb{C}$ such that $u = \sum_{n,k} c_{nk} f_{nk}$ and $u \in H^s(D)$ if and only if

$$\|u\|_{H^s(D)} \approx \left\{ \sum_{n,k} z_{nk}^{2s} |c_{nk}|^2 \right\}^{1/2} < \infty. \quad (5.1)$$

If $s \geq 1/2$, the space defined by (5.1) will be denote by $H_0^s(D)$. Moreover, for a positive integer n and $u \in L^2$

$$(\forall (r, \theta) \in D, u(r, \theta) = e^{in\theta} u(r, 0)) \Leftrightarrow u = \sum_{k \geq 1} c_{nk} f_{nk} \quad (5.2)$$

The following lemma show the asymptotics for the L^p norms of f_{n1} .

Lemma 5.2. *Let $p \in [2, \infty]$. Then $\|f_{n1}\|_{L^p(D)} \approx n^{-\frac{2}{3p} - \frac{1}{3}}$.*

To prove this lemma, we use the properties of the Bessel function. In this talk, we do not show this lemma (see [6, 8].)

Let $\kappa > 0$ and $s \in]1/5, 1/2[$. Set

$$\phi_n = n^{\frac{2}{3}-s} f_{n1},$$

and

$$\omega_n = \frac{\|\phi_n\|_{L^4}^4}{\|\phi_n\|_{L^2}^2}.$$

By Lemma 5.1 and Lemma 5.2, we have that

$$\|\phi_n\|_{H^s} \approx 1, \quad \|\phi_n\|_{L^2} \approx n^{-s}, \quad \omega_n \approx n^{\frac{2}{3}-2s}.$$

If $n \gg 1$, then there exists a unique global solution $u_n(t)$ of (NLS) with the initial data $\kappa\phi_n$. By the L^2 conservation law, we have $\|u_n(t, \cdot)\|_{L^2} = C\kappa n^{-s}$. By the energy conservation law and the Gagliardo-Nirenberg inequality,

$$\begin{aligned} \|\nabla u_n(t, \cdot)\|_{L^2}^2 &\leq -\|\nabla u_n(t, \cdot)\|_{L^2}^2 + \|u_n(t, \cdot)\|_{L^4}^4 + 2\|\nabla \kappa\phi_n\|_{L^2}^2 - \|\kappa\phi_n\|_{L^4}^4, \\ &\leq -\|\nabla u_n(t, \cdot)\|_{L^2}^2 + C\|\nabla u_n(t, \cdot)\|_{L^2}^2 \|u_n(t, \cdot)\|_{L^2}^2 + 2\|\nabla \kappa\phi_n\|_{L^2}^2 - \|\kappa\phi_n\|_{L^4}^4, \\ &\leq -\|\nabla u_n(t, \cdot)\|_{L^2}^2 + Cn^{-2s}\kappa^2\|\nabla u_n(t, \cdot)\|_{L^2}^2 + C\kappa^2 n^{2-2s} + C\kappa^4 n^{\frac{2}{3}-4s}. \end{aligned}$$

Thus, if $n \gg 1$, then $\|u_n(t, \cdot)\|_{H_0^1} \leq C\kappa n^{1-s}$. By an interpolation,

$$\|u_n(t, \cdot)\|_{H^s} \leq \|u_n(t, \cdot)\|_{H_0^1}^s \|u_n(t, \cdot)\|_{L^2}^{1-s} \leq C\kappa.$$

Since $|\phi_n(r, \theta)|^2 \phi_n(r, \theta) = e^{in\theta} |\phi_n(r, 0)|^2 \phi_n(r, 0)$, by (5.2) $|\phi_n|^2 \phi_n = \omega_n \phi_n + r_n$, where $r_n = \sum_{k \geq 2} c_k f_{nk}$. Set

$$u_n(t, x) = \kappa \exp(-it(z_{n1}^2 - \kappa^2 \omega_n)) (\phi_n(x) + w_n(t, x)). \quad (5.3)$$

Then w_n satisfied the following equation

$$\begin{cases} (i\partial_t + \Delta + z_{n1}^2 - \kappa^2 \omega_n) w_n = -\kappa (|\phi_n + w_n|^2 (\phi_n + w_n) - |\phi_n|^2 \phi_n + r_n) \\ w_n(0, x) = 0, \quad x \in D \end{cases} \quad (5.4)$$

Here we estimate the H^s norms of w_n . We decompose

$$w_n(t, x) = \lambda_n(t) \phi_n(x) + q_n(t, x),$$

where

$$q_n(t, x) = \sum_{k \geq 2} c_k(t) f_{nk}(x). \quad (5.5)$$

Estimate of $\|q_n\|_{H^s}$. By conservation law of u_n , we have

$$|1 + \lambda_n(t)|^2 \|\phi_n\|_{L^2}^2 + \|q_n(t)\|_{L^2}^2 = \|\phi_n\|_{L^2}^2, \quad (5.6)$$

while by the energy conservation law we have

$$|1 + \lambda_n(t)|^2 \|\nabla \phi_n\|_{L^2}^2 + \|\nabla q_n(t)\|_{L^2}^2 - \frac{1}{2\kappa^2} \|u_n(t)\|_{L^4}^4 = \|\nabla \phi_n\|_{L^2}^2 - \frac{\kappa^2}{2} \|\phi_n\|_{L^4}^4. \quad (5.7)$$

Using $\|\nabla \phi_n\|_{L^2}^2 = z_{n1}^2 \|\phi_n\|_{L^2}^2$ and calculating (5.7)–(5.6), we have

$$\|\nabla q_n(t)\|_{L^2}^2 - z_{n1}^2 \|q_n(t)\|_{L^2}^2 = \frac{1}{2\kappa^2} \|u_n(t)\|_{L^4}^4 - \frac{\kappa^2}{2} \|\phi_n\|_{L^4}^4 \leq \frac{1}{2\kappa^2} \|u_n(t)\|_{L^4}^4.$$

By (5.6), we have $|\lambda_n(t)| \leq 2$. Thus, by the equation (5.3)

$$|u_n(t, x)|^4 \leq C\kappa^4 (|\phi_n(x)|^4 + |q_n(t, x)|^4), \quad t \in \mathbb{R}, \quad x \in D. \quad (5.8)$$

Due to Lemma 5.1, for $k \geq 2$

$$z_{nk}^2 - z_{n1}^2 = (z_{nk} - z_{n1})(z_{nk} + z_{n1}) \geq Cn^{1/3} z_{nk}. \quad (5.9)$$

Moreover,

$$\|\phi_n\|_{L^4}^4 = \omega_n \|\phi_n\|_{L^2}^2 \approx n^{\frac{2}{3}-4s} \quad (5.10)$$

Using (5.8)-(5.10), we have

$$\begin{aligned}
n^{1/3} \|q_n(t)\|_{H_0^{1/2}}^2 &\leq C n^{1/3} \sum_{k \geq 2} z_{nk} \|c_k(t) f_{nk}\|_{L^2}^2, \\
&\leq C \sum_{k \geq 2} (z_{nk}^2 - z_{n1}^2) \|c_k(t) f_{nk}\|_{L^2}^2, \\
&\leq C (\|\nabla q_n(t)\|_{L^2}^2 - z_{n1}^2 \|q_n(t)\|_{L^2}^2), \\
&\leq \frac{C}{2\kappa^2} \|u_n(t)\|_{L^4}^4, \\
&\leq C \kappa^2 (\|\phi_n\|_{L^4}^4 + \|q_n(t)\|_{L^4}^4) \leq C \kappa^2 n^{\frac{2}{3}-4s} + C \kappa^2 \|q_n(t)\|_{H_0^{1/2}}^4.
\end{aligned}$$

Since $q_n(0, \cdot) = 0$, by a bootstrap argument we obtain

$$\|q_n(t)\|_{H_0^{1/2}} \leq C \kappa n^{\frac{1}{6}-2s}. \quad (5.11)$$

By the Sobolev embedding

$$\|q_n(t)\|_{L^4} \leq C \kappa n^{\frac{1}{6}-2s}. \quad (5.12)$$

Moreover, by (5.5) and (5.11)

$$\|q_n(t)\|_{L^2} \leq C z_{n1}^{-1/2} \|q_n(t)\|_{H_0^{1/2}} \leq C \kappa n^{-\frac{1}{3}-2s}. \quad (5.13)$$

By an interpolation between (5.11) and (5.13), we obtain the estimate

$$\|q_n(t)\|_{H^s} \leq C \|q_n(t)\|_{H_0^{1/2}}^{2s} \|q_n(t)\|_{L^2}^{1-2s} \leq C \kappa n^{-\frac{1}{3}-s}. \quad (5.14)$$

Estimate of $\lambda_n(t)$. We project the equation (5.4) on ϕ_n . Then we have

$$\begin{cases} (i\partial_t - \omega_n \kappa^2) \lambda_n = -\frac{\kappa}{\|\phi_n\|_{L^2}} \{(|\phi_n + w_n|^2(\phi_n + w_n), \phi_n)_{L^2} - (|\phi_n|^2 \phi_n, \phi_n)_{L^2}\} \\ \lambda_n(0) = 0. \end{cases} \quad (5.15)$$

Since $w_n = \lambda_n \phi_n + q_n$, $|\phi_n|^2 \phi_n = \omega_n \phi_n + r_n$ and

$$\begin{aligned}
&(|\phi_n + w_n|^2(\phi_n + w_n), \phi_n)_{L^2} - (|\phi_n|^2 \phi_n, \phi_n)_{L^2} \\
&= - \int (2|\phi_n|^2 w_n + \phi_n^2 \bar{w}_n) \bar{\phi}_n + \int (2\text{Re}(\bar{\phi}_n w_n) w_n \phi_n + |w_n|^2 |\phi_n|^2 + |w_n|^2 |\phi_n|^2 + |w_n|^2 w_n \bar{\phi}_n),
\end{aligned}$$

we decompose the nonlinear term of (5.15) as follows

$$-\frac{\kappa}{\|\phi_n\|_{L^2}} \{(|\phi_n + w_n|^2(\phi_n + w_n), \phi_n)_{L^2} - (|\phi_n|^2 \phi_n, \phi_n)_{L^2}\} = L_1 + L_2 + L_3,$$

where

$$\begin{aligned}
L_1 &= -\kappa^2 (2\omega_n \lambda_n + \omega_n \bar{\lambda}_n), \\
L_2 &= \frac{\kappa^2}{\|\phi_n\|_{L^2}^2} O \left(|\lambda_n|^2 \int |\phi_n|^4 + |\lambda_n|^3 \int |\phi_n|^4 \right), \\
L_3 &= \frac{\kappa^2}{\|\phi_n\|_{L^2}^2} O \left(\int |q_n|^3 |\phi_n| + \int |q_n|^2 |\phi_n|^2 + |(q_n, r_n)_{L^2}| \right).
\end{aligned}$$

First, we estimate the source term L_3 . By (5.12)

$$\frac{\int |q_n|^3 |\phi_n|}{\|\phi_n\|_{L^2}^2} \leq C n^{2s} \|q_n\|_{L^4}^3 \|\phi_n\|_{L^4} \leq C n^{2s} n^{\frac{1}{2}-6s} n^{\frac{1}{6}-s} = C n^{\frac{2}{3}-5s}.$$

Similarly, using (5.12) and (5.13), we obtain

$$\frac{\int |q_n|^2 |\phi_n|^2}{\|\phi_n\|_{L^2}^2} \leq C n^{2s} \|q_n\|_{L^2}^2 \|\phi_n\|_{L^\infty}^2 \leq C n^{-4s},$$

and by $|\phi_n|^2\phi_n = \omega_n\phi_n + r_n$

$$\frac{|(q_n, r_n)_{L^2}|}{\|\phi_n\|_{L^2}^2} \leq \frac{|(q_n, |\phi_n|^2\phi_n)_{L^2}|}{\|\phi_n\|_{L^2}^2} \leq Cn^{\frac{1}{3}-3s}.$$

Since $s \in]1/5, 1/2[$, the equation for λ_n can be written as

$$\begin{cases} i\partial_t\lambda_n = -2\omega_n\kappa^2\text{Re}(\lambda_n) + O(\omega_n|\lambda_n|^2 + \omega_n|\lambda_n|^3 + n^{\frac{1}{3}-3s}), \\ \lambda_n(0) = 0. \end{cases} \quad (5.16)$$

The L^2 conservation law (5.6) yields

$$-2\text{Re}(\lambda_n) - |\lambda_n|^2 = 1 - |1 + \lambda_n|^2 = \frac{\|q_n(t)\|_{L^2}^2}{\|\phi_n\|_{L^2}^2} = O(n^{-\frac{1}{3}-3s}),$$

so we have

$$\begin{cases} i\partial_t\lambda_n = O(\omega_n|\lambda_n|^2 + \omega_n|\lambda_n|^3 + n^{\frac{1}{3}-3s}), \\ \lambda_n(0) = 0. \end{cases} \quad (5.17)$$

Set $\gamma_n = n^{\frac{1}{3}-3s}$ and $M_n(T) := \sup_{t \in [0, T[} \gamma_n^{-1}|\lambda_n|$. Then by integrating (5.17), we have that

$$\begin{aligned} M_n(T) &\leq CT(1 + \gamma_n\omega_n(M_n(T))^2 + \gamma_n^2\omega_n(M_n(T))^3), \\ &\leq CT(1 + n^{1-5s}((M_n(T))^2 + n^{\frac{3}{4}-7s}(M_n(T))^3)). \end{aligned}$$

Since $s > 1/5$ and $M_n(0) = 0$, we obtain that $M_n(T) \leq CT$ for n large enough with respect to T . Thus,

$$|\lambda_n(t)| \leq CTn^{1-5s}. \quad (5.18)$$

Therefore, by (5.14) and (5.18) the proof Theorem 3.2 is complete.

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