



8.2 Similarity and diagonalizability

Coordinate change for diagonalization

Similar matrices

Definition 8.2.1 If A and C are square matrices with the same size, then we say that C is *similar to* A if there is an invertible matrix P such that $C = P^{-1}AP$.

- $A \approx B, B \approx C \rightarrow A \approx C. A \approx A. A \approx B \rightarrow B \approx A$

Theorem 8.2.2 *Two matrices are similar if and only if there exist bases with respect to which the matrices represent the same linear operator.*

- Proof: $C = P^{-1}AP$. If $P = [v_1, \dots, v_n]$, then by equation (20) Sec.8.2, we have $[T]_B = P^{-1}[T]P$ where $[T] = A$.

Similarity Invariants

- Coordinate change are superficial change.
- Many essential properties remain.
- $\det(P^{-1}AP) = \det(P)^{-1} \det(A) \det(P) = \det(A)$.

Theorem 8.2.3

- (a) *Similar matrices have the same determinant.*
- (b) *Similar matrices have the same rank.*
- (c) *Similar matrices have the same nullity.*
- (d) *Similar matrices have the same trace.*
- (e) *Similar matrices have the same characteristic polynomial and hence have the same eigenvalues with the same algebraic multiplicities.*

- Example 1.



Eigenvectors and eigenvalues of similar matrices

- The algebraic multiplicity of an eigenvalue is the multiplicity as a root of the characteristic polynomial.
- The geometric multiplicity of an eigenvalue is the dimension of $(\lambda I - A)x = 0$.
- geom mult. \leq alg. mult.
- Example 2.

Theorem 8.2.4 *Similar matrices have the same eigenvalues and those eigenvalues have the same algebraic and geometric multiplicities for both matrices.*

- **Proof: $C=P^{-1}AP$. Then**
 - $LI-C=LI-P^{-1}AP = P^{-1}(LI-A)P$.
 - $\det(LI-C)=\det(LI-A)$.
 - $(LI-C)x=0 \Leftrightarrow P^{-1}(LI-A)Px=0. \Leftrightarrow (LI-A)y=0$
for $y=Px$. (substitute variable)
 - Thus $\dim \text{sol } (LI-C)x=0$ is the same
as $\dim \text{sol}(LI-A)x=0$.

Theorem 8.2.5 Suppose that $C = P^{-1}AP$ and that λ is an eigenvalue of A and C .

(a) If \mathbf{x} is an eigenvector of C corresponding to λ , then $P\mathbf{x}$ is an eigenvector of A corresponding to λ .

(b) If \mathbf{x} is an eigenvector of A corresponding to λ , then $P^{-1}\mathbf{x}$ is an eigenvector of C corresponding to λ .


- Proof (b): $A\mathbf{x} = L\mathbf{x} \rightarrow P^{-1}A\mathbf{x} = LP^{-1}\mathbf{x} \rightarrow P^{-1}AP(P^{-1}\mathbf{x}) = L(P^{-1}\mathbf{x}) \rightarrow C(P^{-1}\mathbf{x}) = L(P^{-1}\mathbf{x})$.

Diagonalization

- We wish to change coordinates so that the matrix is diagonal.
- This is not always possible.

The Diagonalization Problem Given a square matrix A , does there exist an invertible matrix P for which $P^{-1}AP$ is a diagonal matrix, and if so, how does one find such a P ? If such a matrix P exists, then A is said to be *diagonalizable*, and P is said to *diagonalize* A .

Theorem 8.2.6 *An $n \times n$ matrix A is diagonalizable if and only if A has n linearly independent eigenvectors.*

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- Proof \rightarrow : $A=P^{-1}DP$ for a diagonal matrix D with diagonals L_1, L_2, \dots, L_n .
 - $AP=PD$. $P=[p_1, p_2, \dots, p_n]$
 - $AP=[Ap_1, Ap_2, \dots, Ap_n]$
 - $PD=[L_1p_1, L_2p_2, \dots, L_np_n]$
 - Thus $Ap_i=L_ip_i$.
 - Proof \leftarrow : p_1, p_2, \dots, p_n linearly independent, eigenvectors.
 - $Ap_i=L_ip_i$.
 - Let $P=[p_1, p_2, \dots, p_n]$.
 - The same computations show $AP=PD$.
 - Since P is invertible, $P^{-1}AP=D$.

A method for diagonalizing a matrix.

Diagonalizing an $n \times n$ Matrix with n Linearly Independent Eigenvectors

Step 1. Find n linearly independent eigenvectors of A , say $\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_n$.

Step 2. Form the matrix $P = [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_n]$.

Step 3. The matrix $P^{-1}AP$ will be diagonal and will have the eigenvalues corresponding to $\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_n$, respectively, as its successive diagonal entries.

- Example 4.

Linear independence of eigenvectors

Theorem 8.2.7 *If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ are eigenvectors of a matrix A that correspond to distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$, then the set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is linearly independent.*

- Thus, if some eigenvalues coincide, the corresponding eigenvectors may be dependent. (This is unless they are fundamental solutions.)

Some facts

Theorem 8.2.8 *An $n \times n$ matrix with n distinct real eigenvalues is diagonalizable.*

Theorem 8.2.9 *An $n \times n$ matrix A is diagonalizable if and only if the sum of the geometric multiplicities of its eigenvalues is n .*

Theorem 8.2.10 *If A is a square matrix, then:*

- (a) The geometric multiplicity of an eigenvalue of A is less than or equal to its algebraic multiplicity.*
- (b) A is diagonalizable if and only if the geometric multiplicity of each eigenvalue of A is the same as its algebraic multiplicity.*



- Unifying theorem:

Theorem 8.2.11 *If A is an $n \times n$ matrix, then the following statements are equivalent.*

- (a) *A is diagonalizable.*
- (b) *A has n linearly independent eigenvectors.*
- (c) *\mathbb{R}^n has a basis consisting of eigenvectors of A .*
- (d) *The sum of the geometric multiplicities of the eigenvalues of A is n .*
- (e) *The geometric multiplicity of each eigenvalue of A is the same as the algebraic multiplicity.*