# **1** Introduction

# Outline

- The deformation space of (X, G)-structures on an orbifold.
  - Definition
  - The local homeomorphism theorem
    - \* The isotopy lemma
    - \* Proof.

#### Some helpful references

- S. Choi, Geometric structures on orbifolds and holonomy representations, Geometriae Dedicata 104: 161 199, 2004.
- W. Thurston, Lecture notes...: A chapter on orbifolds, 1977.
- R. Canary, D. Epstein, and P. Green, Notes on notes of Thurston, In: London Math. Soc. Lecture Note Ser. 111, Cambridge University Press, Cambridge, 1987, pp. 3 92.
- W. Lok, Deformations of locally homorgeneous spaces and kleinian groups, PhD Thesis, Columbia University, 1984.

# **2** Definition

#### Definition of the deformation space of (X, G)-structures on orbifolds

- Consider the set  $\mathcal{M}(M)$  of all (X, G)-structures on an orbifold M.
- We introduce an equivalence relation  $\sim$ : two (X, G)-structures  $\mu_1$  and  $\mu_2$  are equivalent if there is an isotopy  $\phi : M \to M$  so that  $\phi^*(\mu_1) = \mu_2$ .
- The deformation space of (X, G)-structures on M is  $\mathcal{M}/\sim$ .
- We reinterpret the space as
  - The set of diffeomorphisms  $f:M\to M'$  for M an orbifold and M' an (X,G)-orbifold.
  - The equivalence relation  $f : M \to M'$  and  $g : M \to M$ " if exists an (X, G)-diffeomorphism  $h : M' \to M$ " so that  $h \circ f$  is isotopic to g.
  - The quotient space is same as above.

## Another interpretations

- Identify  $\pi_1(M)$  with  $\pi_1(M \times I)$ .
- Consider the set of diffeomorphisms  $f: \tilde{M} \to \tilde{M}'$  equivariant with respect to isomorphism  $f_*: \pi_(M) \to \pi_1(M')$  for an (X, G)-orbifold M'.
- We introduce an equivalence relation: Given f : M̃ → M̃' and g : M̃ → M̃", we say that they are equivalent if there exists an (X, G)-map φ : M̃' → M̃" so that φ ∘ f is isotopic to g by an isotopy M̃ × I → M̃" equivariant with respect to both φ<sub>\*</sub> ∘ f<sub>\*</sub> and g<sub>\*</sub> which are equal.
- Denote this set by  $\mathcal{D}_I(M)$ .
- This set is again one-to-one relation with the above space since we can always lift diffeomorphisms and isotopies.

#### Isotopy-equivalence space.

- $\mathcal{S}(M)$  is defined as follows.
- Consider the set of (D, f̃ : M̃ → M̃') where f : M → M' is a diffeomorphism for orbifolds M and M' and D : M̃' → X is a diffeomorphism equivariant with respect to a homomorphism h : π<sub>1</sub>(M') → G.
- Two (D, f̃) and (D', f̃': M̃ → M̃") are equivalent if there is a diffeomorphism φ: M' → M" so that D' ∘ φ̃ = D and an isotopy H : M × I → M" equivariant with respect to f̃'<sub>\*</sub> : π<sub>1</sub>(M) → π<sub>1</sub>(M") so that φ ∘ f = H<sub>0</sub> and f' = H<sub>1</sub>.
- We can finally give topology on this space by  $C_1$  topology using  $D \circ \tilde{f}$ .

#### The topology of the deformation space

- There is a natural action of G on  $\mathcal{S}(M)$  given by  $g(D, \tilde{f}) = (g \circ D, \tilde{f}), g \in G$ .
- The quotient space  $\mathcal{D}(M)$  is the deformation space.
- Proof:
  - We show  $\mathcal{D}_I(M)$  is one-to-one equivalent to  $\mathcal{S}(M)/G$ .
  - Given an element  $\tilde{f}: \tilde{M} \to \tilde{M}'$ , there is a developing map  $D: \tilde{M}' \to X$  equivariant with respect to  $h: \pi_1(M') \to G$
  - If *f̃* : *M̃* → *M̃* ' and *f̃* ' : *M̃* → *M̃* " are equivalent, then there is an (X, G)-diffeomorphism M' → M" and hence two global charts D' and D" differ only by an element of G.
  - Conversely, given (D, f), we obviously obtain an (X, G)-structure on M'.
  - If  $(D, \tilde{f})$  and  $(D', \tilde{f}')$  are equivalent, then there is a diffeomorphism  $\phi : M' \to M''$  so that  $D' \circ \tilde{\phi} = g \circ D$ . This means  $\phi' : M' \to M''$  is an (X, G)-diffeomorphism.

# 2.1 The local homeomorphism theorem

#### The representation space

- Suppose that  $\pi$  is finitely-presented. In particular if M is a compact n-orbifold, this is true.
- Denote by  $g_1, ..., g_n$  the set of generators and  $R_1, ..., R_m$  be the set of relations.
- The set of homomorphisms π<sub>1</sub>(M) → G can be identified with a subset of G<sup>n</sup> by sending a homomorphism h to (h(g<sub>1</sub>),...,h(g<sub>n</sub>)). This clearly injective map.
- This image can be described as an algebraic subset defined by relations  $R_1, ..., R_m$ .
- This follows since if the relation is satisfied, then we can obtain the representation conversely.
- Denote the space by  $Hom(\pi, G)$ .
- There is an action of G on  $Hom(\pi, G)$  given by the action  $(g \star h)(\cdot) = gh(\cdot)g^{-1}$
- We denote by  $Rep(\pi, G)$  the quotient space  $Hom(\pi, G)/G$ .

#### The map hol

- We can define  $PH : \mathcal{S}(M) \to Hom(\pi, G)$ . The main purpose of this section is to show that PH is a local homeomorphism.
- We send (D, f) to the associated homomorphism  $h : \pi \to G$ .
- *PH* is continuous: If D' ∘ f̃' is sufficiently close to D ∘ f in a sufficiently large compact subset of M̃, then the holonomy h'(g<sub>i</sub>) of generators g<sub>i</sub> is as close to the original h(g<sub>i</sub>) as possible.
- The local homeomorphism result was very important for the study of deformations of (X, G)-structures on manifolds, as first observed by Weil. The same can be said for orbifolds.
- For manifolds, Thurston gave a proof. Later J. Morgan gave a lecture of it, which is written up by in his Ph.D. thesis. Also, Canary and Epsten gave a proof of it also.

## The stable representations

- There is a dense open subset, called the stable subset, of Hom(π, G) where G acts properly. Denote this space by Hom<sup>s</sup>(π, G) and its quotient by Rep<sup>s</sup>(π, G).
- If we denote by D<sup>s</sup>(M) the subset of D whose holonomies are in the stable region. Then there is a local homeomorphism hol : D<sup>s</sup>(M) → Rep<sup>s</sup>(π, G) since the right action on developing map gives a conjugation action on holonomy homomorphisms.

# 2.2 The proof of the local homeomorphism

## The isotopy lemma

- Each point of  $Hom(G_x, G)$  has a neighborhood S which is a cone over a semialgebraic set. Here  $G_x$  is a stabilizer group or any other finitely presented group.
- Let F be a compact subset of an open ball B. Let  $G_B$  be a finite group acting on F and B. Let S be a cone-neighborhood of an element of  $Hom(G_B, G)$ .
  - Let  $H: F \times [0, \epsilon] \times S \to X$  be a map such that  $H(h): F \times [0, \epsilon'] \to X$  is a  $G_B$  equivariant isotopy for each  $h' \in S$ .
  - Then there exists an extention  $H' : B \times [0, \epsilon''] \to X$  which is a  $G_B$  equivariant isotopy.

# The outline of the proof

- Step I: we realize the orbifold M as a union of model open sets. We choose covers  $\{U_1, ..., U_k\}, \{W_1, ..., W_k\}, \{V_1, ..., V_k\}$  such that  $Cl(U_i) \subset W_i, Cl(W_i) \subset V_i$ : One can choose nice covering which are model neighborhoods.
- Step II: We define a section  $s : O \subset Hom(\pi_1(M_0), G) \to \mathcal{S}(M_0)$  so that  $PH \circ s$  is the identity. This is accomplished by deforming model neighborhoods and patching conjugating diffeomorphisms.
- Step III: We show that *PH* is locally injective. From this it follows that *PH* is a local homeomorphism.

## Step II

- We choose O as a cone-neighborhood of a point in the representation space.
- We identify  $V_i$  with open subsets of X and find the conjugating diffeomorphisms.
- We identified the deformed  $V_i$  by  $V'_i$ . If we choose  $V_i$ s well and take sufficiently small deformations, then the result is an orbifold, call it M'.
- We will show that M' is diffeomorphic to M.
  - We can use  $U_i$ s to obtain M' as well.
  - Now defined maps from the highest intersection set of  $U_i$ . The number will be n + 1 if M has dimension n.
  - Define inductively from n + 1-intersections and n-intersections and so on.
- •

# The step III

- In this step, we show *PH* is locally injective.
  - We control the size of O so that for sufficiently small O, s(O) is contained in any given small open neighborhood of original (X, G)-isotopy class.
  - Next, if the image under PH is the same two points for a small open neighborhood of  $\mathcal{S}(M)$ , then we can find an orbifold-diffeomorphism between the two that is very close to identity in the  $C_1$ -sense.
  - Now use the exponential map on  $\tilde{M}$  to obtain an isotopy of this map to identity.
  - This proves the injectivity.
- The local homeomorphism property of *PH* follows by seeing that the section *s* can be defined on open subsets which maps into a given neighborhood. Thus, an image of an open set is open.