

Concept Learning

- **concept**

some subset of objects or events defined over a large set
example.

the subset of animals that constitute birds

representation of concept:

a boolean valued function defined over a large set

example.

a function defined over all animals, whose value is true (1) for birds and false (0) for other animals

- **learning**

inducing general functions from specific training examples

- **concept learning (or category learning)**

acquiring the definition of general category given a sample of positive and negative training examples of category, that is, inferring a boolean-valued function from training examples of its input and output

- a concept learning task

. target concept: EnjoySport

(days on which Aldo enjoys water sport)

. hypothesis: a vector of six constraints,

specifying the value of six attributes, they are,

Sky (Sunny/Cloudy/Rainy), AirTemp (Warm/Cold),

Humidity (Normal/High), Wind (Strong/Weak),

Water (Warm/Cool), Forecast (Same/Change)

for each attribute, the hypothesis will either

? (don't care: any value is acceptable),

discrete values, or

\emptyset (null: no value is acceptable)

example.

<?, Cold, High, ?, ?, ?>

-> "Aldo enjoys sport only on cold days with high humidity."

<?, ?, ?, ?, ?, ?>

-> "Aldo always enjoys sport." (most general hypothesis)

< \emptyset , \emptyset , \emptyset , \emptyset , \emptyset , \emptyset >

-> "Aldo does not enjoy sport at all." (most specific case)

. Positive and negative training examples for the target concept EnjoySport

Example	Sky	AirTemp	Humidity	Wind	Water	Forecast	EnjoySport
1	Sunny	Warm	Normal	Strong	Warm	Same	Yes
2	Sunny	Warm	High	Strong	Warm	Same	Yes
3	Rainy	Cold	High	Strong	Warm	Change	No
4	Sunny	Warm	High	Strong	Cool	Change	Yes

What is *the general concept* for these examples?

Given

instances X : possible days, each described by six attribute,

target function $c: \text{EnjoySport } X \rightarrow \{0, 1\}$,

hypothesis H : conjunction of literals such as

$\langle ?, \text{Cold}, \text{High}, ?, ?, ? \rangle$, and

training examples D : positive and negative examples of the target function, that is,

$\langle X_1, c(X_1) \rangle, \dots, \langle X_m, c(X_m) \rangle$,

determine

a hypothesis h in H such that

$h(x) = c(x)$ for all x in X .

- **inductive learning hypothesis**

Any hypothesis found to be approximate the target function well over *a sufficiently large set training examples* will also approximate the target function well over *other unobserved examples*.

- **concept learning as search**

find a hypothesis that best fits training examples
search space in EnjoySport:

$$\text{number of instances} = 3 \cdot 2^5 = 96$$

$$\text{number of hypotheses} = 5 \cdot 4^5 = 5120$$

- **general-to-specific ordering**

. Let $x \in X$ and $h \in H$. Then,

x satisfies h if and only if $h(x) = 1$.

. Let h_j and h_k be boolean-valued functions defined over X . Then,

h_j is *more_general_than_or_equal_to* h_k

$(h_j \geq_g h_k)$ if and only if

$$(\forall x \in X)[(h_k(x) = 1) \rightarrow (h_j(x) = 1)].$$

h_j is *(strictly) more_general_than* h_k ($h_j >_g h_k$)

if and only if

$$(h_j \geq_g h_k) \wedge \neg(h_k \geq_g h_j).$$

example.

$h_j = \langle \text{Sunny}, ?, ?, ?, ?, ? \rangle >_g h_k = \langle \text{Sunny}, ?, ?, \text{Strong}, ?, ? \rangle$

→ h_j is more_general_than h_k . or

→ h_k is more_specific_than h_j .

Here, the problem is how to search the good hypothesis using this hypothesis ordering.

One of such candidates is Find-S algorithm in which the maximally specific hypothesis is searched.

- Find-S algorithm

Step 1. Initialize h to the most specific hypothesis in H , that is,

$h = \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle$.

Step 2. For each **positive training instance** x

- for each attribute constraint a_i in h

if the constraint a_i in h is satisfied by x , do nothing

else replace a_i in h by the next more general constraint

that is satisfied by x .

Step 3. Output h .

example.

$h_0 = \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle$.

$x_1 = \langle \text{Sunny, Warm, Normal, Strong, Warm, Same} \rangle +$

$h_1 = \langle \text{Sunny, Warm, Normal, Strong, Warm, Same} \rangle$

$x_2 = \langle \text{Sunny, Warm, High, Strong, Warm, Same} \rangle +$

$h_2 = \langle \text{Sunny, Warm, ?, Strong, Warm, Same} \rangle$

$x_3 = \langle \text{Rainy, Cold, High, Strong, Warm, Change} \rangle -$

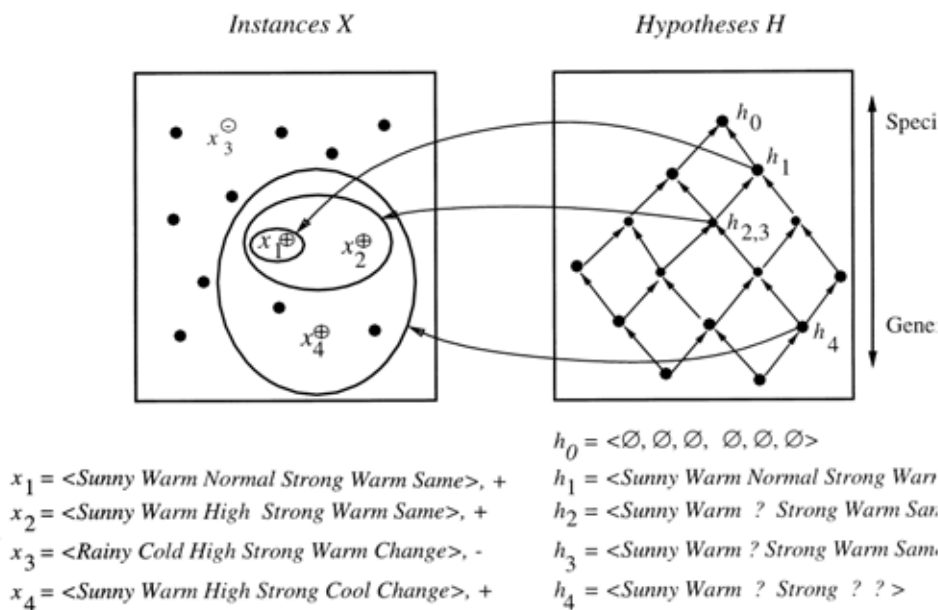
$h_3 = h_2$

$x_4 = \langle \text{Sunny, Warm, High, Strong, Cool, Change} \rangle +$

$h_4 = \langle \text{Sunny, Warm, ?, Strong, ?, ?} \rangle$

... ..

Hypothesis space searched by Find-S algorithm



- **problem in Find-S algorithm**

- . can't tell whether it has the learned concept.
- . can't tell when training data are inconsistent.
- . picks a maximally specific h .
- . depending on H , there might be several.

-> Find-S algorithm only uses the positive examples.

-> We better find *the proper hypothesis space* rather than a specific hypothesis.

-> the concept of version spaces

Reference: Machine Learning, chapter 2.