

1 Introduction

About this lecture

- $PSL(2, C)$ and hyperbolic 3-spaces.
- Subgroups of $PSL(2, C)$
- Hyperbolic manifolds and orbifolds
- Examples
- 3-manifold topology and Dehn surgery
- Rigidity
- Volumes and ideal tetrahedra
- Part 1: 1.1-1.4 Kleinian group theory
- Part 2: 1.5-1.7 Topology

Some helpful references

- Ratcliffe, Foundations of hyperbolic manifolds, Springer (elementary)
- K. Matsuzaki, M. Taniguchi, Hyperbolic manifolds and Kleinian groups, Oxford (complete but technical)
- A. Marden, The geometry of finitely generated Kleinian groups, Ann of Math, 99 (1974) 299-323. (nice but more advanced)
- K. Ohshika, Discrete groups, AMS
- A. Adem, j. Leida, ... Orbifolds and stringly topology, Cambridge.
- W. Thurston, Three-dimensional geometry and topology I, Princeton University Press.
- W. Thurston, Lecture notes, (This is hard to read and incomplete)

Some helpful references

- <http://www.math.uiuc.edu/~nmd/computop/index.html> These include many computational tools for finding hyperbolic manifolds. (SnapPy, originally SnapPea by J. Weeks)
- <http://www.geom.uiuc.edu/~crobles/hyperbolic/> Interactive Javalets for experiments.
- <http://www.geometrygames.org/SnapPea/>

- <http://www.ms.unimelb.edu.au/~snap/orb.html> Snap, Orb (exact alg. computations, computations for orbifolds)
- <http://www.neverendingbooks.org/index.php/the-dedekind-tessellation.html> Modular groups

2 General introduction

The field of geometry and topology: geometric structures

- Basically, we try to understand the relationship between manifolds (orbifolds, varieties, ...) with discrete subgroup of Lie groups acting on homogeneous (or nice) spaces.
- Algebraic representations are often possible (Geometrization)
- Often such representations might be unique (rigidity, Margulis, Mostow) (Arithmeticity places an important role here.)
- If not, we have moduli spaces. (Teichmuller spaces)
- We obtain invariants in this way (volume, eta invariants, numerical invariants,...)
- Properties of groups can be studied using topological and geometric methods (group decompositions and Gromov hyperbolicity)
- Thus, there are some correspondences between topology and algebra here.

Manifolds

- Manifolds: Hausdorff, covered by countable euclidean open balls. (2, 3-dim only)
- Main objectives is to make sense of their variety.
- Examples:
 - knot complements. The variety of these are surprisingly many. (still cannot classify)
 - Surfaces: classified by orientation, genus, and number of holes (homology theory is needed)
 - 3-manifolds: Geomerization now makes the field into something of “algebraic problems”.

Geometrization of Manifolds

- If M is an orientable surface, then M can be written \mathbb{H}^2/Γ , E^2/Γ , or S^2/Γ by the uniformization theorem. This is not unique. So we need Teichmüller spaces.
- If M is an orientable compact 3-manifold, then M can be canonically decomposed by spheres, disks into irreducible 3-manifolds.
- Irreducible 3-manifolds decomposes along tori into open or closed submanifolds admitting one of eight geometric structures S^3/Γ , E^3/Γ , \mathbb{H}^3/Γ , Nil/Γ , Sol/Γ , $\widetilde{SL}(2, \mathbb{R})/\Gamma$, $\mathbb{H}^2 \times \mathbb{R}/\Gamma$, and $\mathbf{S}^2 \times \mathbb{R}/\Gamma$.
- The hyperbolic pieces are most varied.

Orbifolds

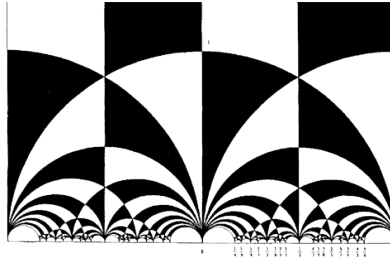
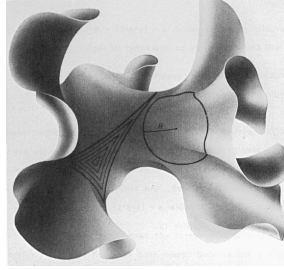
- Orbifolds: Hausdorff, covered by countable quotients of open balls by finite linear group actions that remember the action and the open balls. (Manifolds “are” orbifolds)
- Orbifolds are of form M/Γ where M is a universal covering orbifold and Γ is a properly discontinuous action (not free).
- Given an orbifold O , we can always find M and Γ and the orbifold structure is equivalent to the pair (M, Γ) .
- If M is a manifold, then M/Γ is a *good orbifold*.
- If M is a compact 2-dim orbifold, then M is classified by orbifold Euler characteristic.
- If M is a compact 3-dim orbifold, then M satisfies the geometrization.

Orbifolds

- Sometimes $O = N/\Gamma$ for a manifold N and Γ finite. The O is *very good*.
- Selberg’s Lemma: If Γ is a finitely generated subgroup of $GL(N, \mathbb{C})$, then it has a torsion-free finite index subgroup.
- Most orbifolds here are very good.

3 $PSL(2, \mathbb{C})$ and hyperbolic 3-space

- <http://www.geom.uiuc.edu/docs/forum/hype/model.html>
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$PSL(2, \mathbb{C})$ and hyperbolic 3-space

- $PSL(2, \mathbb{C}) = SL(2, \mathbb{C})/\{\pm I\}$.
- $PSL(2, \mathbb{C})$ acts on $\hat{\mathbb{C}} = \mathbb{C} \cup \{\infty\}$ by $z \mapsto \frac{az+b}{cz+d}$.
- \mathbb{H}^3 is defined as $\{(x, y, t) \in \mathbb{R}^3 | t > 0\}$.
- $t = 0$ plane is identified with \mathbb{C} .
- \mathbb{H}^3 compactifies to a closed ball with boundary $\hat{\mathbb{C}}$ in the compactification of \mathbb{R}^3 as $\hat{\mathbb{R}}^3 = \mathbb{R}^3 \cup \{\infty\}$.
- The boundary set is the sphere of infinity $\mathbb{S}^{2,\infty} := \hat{\mathbb{C}}$ with a complex structure.
- Each Möbius transformation on $\mathbb{S}^{2,\infty}$ extends to an action in \mathbb{R}^3 (Poincaré extension) This is obtained by inversions in spheres perpendicular to $t = 0$ or the the planes perpendicular to $t = 0$.
- The Möbius transformations form the isometry group of the Riemannian metric given by δ_{ij}/t^2 .
- The angles are same as the euclidean angles.
- $PSL(2, \mathbb{C})$ is isomorphic to $\text{Isom}^+(\mathbb{H}^3)$. (Lie group)
- Geodesics are half circles perpendicular to $\mathbb{S}^{2,\infty}$ or a straight line parallel to the t -axis.

- Totally geodesic subspaces are either hemispheres or half-spaces parallel to t -axis.
- Horospheres are given by $t = \text{const}$ or its images under isometries. The images are spheres tangent to $t = 0$ or planes.
- In fact all isometries are generated by reflections. (Möbius type inversion actually)
- Volume form $dx \wedge dy \wedge dt$.
- Models <http://www.geom.uiuc.edu/~crobles/hyperbolic/>

\mathbb{H}^2

- Consider setting $y = 0$. Then we obtain \mathbb{H}^2 with metric δ_{ij}/t^2 .
- This is a totally geodesic subspace. In fact, any other $2D$ -totally geodesic subspace is isometric to it.
- $\text{PSL}(2, \mathbb{R})$ isomorphic to $\text{Isom}^+(\mathbb{H}^2)$.
- the angles, geodesics, subspaces.
- Isometries are generated by reflections.
- Volume form $dx \wedge dt$.
- The boundary is a circle $\hat{\mathbb{R}} = \mathbb{R} \cup \{\infty\}$ in $\hat{\mathbb{R}}^3$.
- Geodesics: <http://www.geom.uiuc.edu/~crobles/hyperbolic/hypr/modl/uhp/uhpjava.html>
- Distances: <http://www.geom.uiuc.edu/~crobles/hyperbolic/hypr/modl/uhp/eq.html>

Alternative view as a hyperboloid in the Lorentzian 4-space

- Let V be a four dimensional space with a quadratic form $q(\vec{x}) = x_1^2 + x_2^2 + x_3^2 - x_4^2$.
- V is decomposed into three parts $q > 0$, the positive open cone C^+ with $q < 0, x_4 > 0$, the negative open cone $q < 0, x_4 < 0$, and the null cone $q = 0$.
- The vectors are called spacelike, positive timelike, negative timelike, or null.
- A hyperboloid is given by $q = -1$.
- We take the upper part Λ . Then the q restricts to Riemannian metric. Then Λ is isometric with \mathbb{H}^3 .
- Define $O^+(V, q) = O^+(1, 3)$ be the orthogonal map preserving C^+ .

- This group is generated by the Lorentzian reflection through time-like hyperplanes.
- $\text{Isom}\Lambda = PO^+(V, q)$ and $\text{Isom}^+\Lambda = PSO^+(V, q)$. These are isomorphic to the previous groups.

Poincare model

- Consider the unit ball B^3 in \mathbb{R}^3 . There is an inversion sending \mathbb{H}^3 onto B^3 .
- The metric is given by $4\delta_{ij}/(1 - |r|^2)^2$.
- Again the isometry group is generated by reflections in spheres orthogonal to ∂B^3 .
- The unit disk B^2 is identified with the hyperbolic plane.

The hyperbolic trigonometry

- hyperbolic law of sines:

$$\sin A / \sinh a = \sin B / \sinh b = \sin C / \sinh c$$

- hyperbolic law of cosines:

$$\begin{aligned} \cosh c &= \cosh a \cosh b - \sinh a \sinh b \cos C \\ \cosh c &= (\cosh A \cosh B + \cos C) / \sinh A \sinh B \end{aligned}$$

- The triangles behave in a funny way... <http://www.math.ksu.edu/~bennett/gc/tri.html>

4 Subgroups of $\text{PSL}(2, \mathbb{C})$

The classifications of elements

- Assume $\gamma \neq I$.
- γ is elliptic if $|\text{tr}\gamma| < 2$.
- γ is parabolic if $\text{tr}\gamma = \pm 2$.
- γ is loxodromic otherwise.
- γ is elliptic if and only if it fixes a unique geodesic and if and only if it is conjugate to $z \mapsto e^{i\theta}z$ for $\theta \neq 0$.
- γ is loxodromic if and only if it acts on a unique geodesic and if and only if it is conjugate to $z \mapsto vz$ where v is a complex number whose length is not 1. (hyperbolic if v is a positive real number)
- γ is parabolic if and only if it acts on horospheres and if and only if it is conjugate to $(x, y, t) \rightarrow (x + a, y + b, t)$ for some real numbers a, b not both zero. (This fixes a unique point of the tangency)

Some more general theory in terms of symmetric space theory

- \mathbb{H}^3 is a symmetric space of the Lie group $PSL(2, \mathbb{C})$ with maximal compact group $PSU(2, \mathbb{C})$ isomorphic to $SO(3, \mathbb{R})$.
- A parabolic subgroup is a subgroup fixing an infinity and acts on leaves of foliation given by a disjoint collection of horospheres. This is conjugate to a group of upper triangular matrices.
- \mathbb{H}^3 can be compactified by adding one point for each parabolic subgroup.
- A geodesic ends at a point of infinity and Busemann function gives us a parameter of horospheres. <http://eom.springer.de/b/b120550.htm>
- This description agrees with the above.
- Reference: Eberlein, Spaces of nonpositive curvature, Chicago

Subgroups of $PSL(2, \mathbb{C})$

- A subgroup is *reducible* if it fixes a unique point in $\hat{\mathbb{C}}$.
- A subgroup is *elementary* if it has a finite orbit in its action on $\mathbb{H}^3 \cup \hat{\mathbb{C}}$. Otherwise it is *non-elementary*.
- Every non-elementary subgroup contains infinitely many loxodromic element, no two of which have a common fixed point.
- Let x, y be elements of $PSL(2, \mathbb{C})$. Then $\langle x, y \rangle$ is reducible if and only if $tr[x, y] = 2$.
-

Kleinian group

- A *Kleinian* group is a discrete subgroup of $PSL(2, \mathbb{C})$.
- In this setting, the discreteness implies that Γ acts properly discontinuously (possibly with fixed points)
- Usually, we assume that it is non-elementary.
- \mathbb{H}^3/Γ is a 3-dimensional orbifold (3-manifold if no torsion).
- We give two-dimensional examples. But they also act on \mathbb{H}^3 as a Kleinian group (called Fuchsian group).
- Fuchsian group can be deformed to quasi-Fuchsian groups.

Triangle groups

- Find a triangle in \mathbb{H}^2 with angles submultiples of π .
- We divide into three cases $\pi/a + \pi/b + \pi/c < 0$.
- In fact, given a surface (or 2-orbifold) S with $\chi < 0$, we have $S = \mathbb{H}^2/\Gamma$ for a Fuchian group.
- Example: once-punctured torus group by Wada <http://vivaldi.ics.nara-wu.ac.jp/~wada/OPTi/index.html>
- $(2, 4, 8)$ -triangle group

The modular group $PSL(2, \mathbb{Z})$ action on \mathbb{H}^2 .

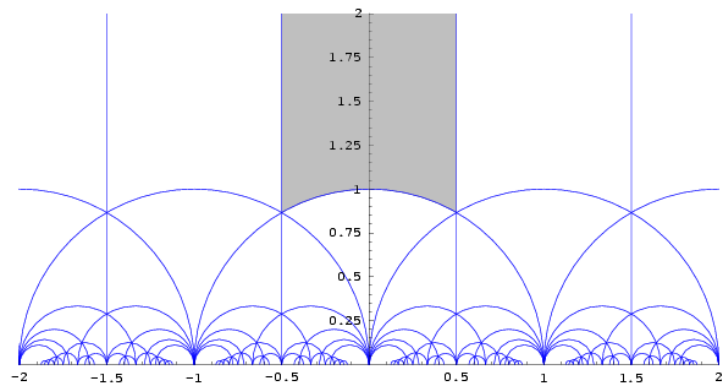
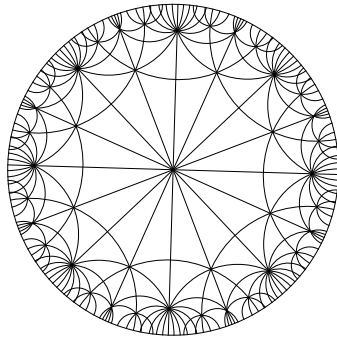
- Generated by $S : z \mapsto -1/z, T : z \mapsto z + 1$.
- $(2, 3, \infty)$ -triangle group.

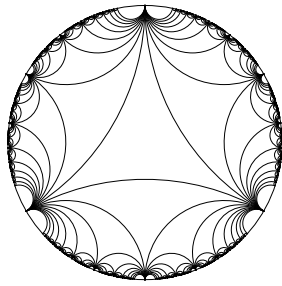
Kleinian group

- Let Γ be a nonelementary Kleinian group.
- A stabilizer of a point of \mathbb{H}^3 is a finite subgroup.
- A stabilizer of a point of the sphere of infinity $\mathbb{S}^{2,\infty}$ can be conjugated to a subgroup B with upper triangular matrices.
- B can be of the following form:
 - Finite cyclic. (if it is finite)
 - A finite extension of an infinite cyclic group generated by a loxodromic or parabolic element. (if it contains a loxodromic)
 - A finite extension of $\mathbb{Z} \oplus \mathbb{Z}$ generated by two parabolic elements.
 - Essentially proved from 2-dim Bieberbach theorem.

Cusp

- A point ζ of $\mathbb{S}^{2,\infty}$ is a cusp point of Γ if the stabilizer consists of parabolic elements and the identity. (rank = 2)
- We will usually be working in finite volume case. So we do not need to know "limit set". the domain of discontinuity in $\mathbb{S}^{2,\infty}$.
- See ideal triangle examples.
- The ideal example <http://egl.math.umd.edu/software.html>





Fundamental domain

- A fundamental domain F for a Kleinian group Γ is a closed subset of \mathbb{H}^3 satisfying
 - $\bigcup_{\gamma \in \Gamma} \gamma F = \mathbb{H}^3$.
 - $F^o \cap \gamma F^o = \emptyset$ if $\gamma \neq I$.
 - the boundary of F has measure zero.
- F is usually a polyhedron (compact or noncompact, finite or infinite sided)

Dirichlet domains

- A Kleinian group Γ , choose a point p (not fixed)
- $D_p(\Gamma) := \{q \in \mathbb{H}^3 \mid d(q, p) \leq d(\gamma(q), p) \text{ for all } \gamma \in \Gamma\}$.
- This is a polyhedron with locally finite sides.
- Sides are bisectors of p and $\gamma(p)$ for some γ .
- The triangles in the triangle reflection groups are Dirichlet domains.

Geometrical finiteness

- A Kleinian group is *geometrically finite* if it admits a finite sided Dirichlet domain for every (some) points. (Another way is the thick part of the convex hull is finite volume)
- Γ is *cocompact* if \mathbb{H}^3/Γ is compact. This is true if and only if all/some Dirichlet domain is compact. (See triangle groups)
- Γ is of *finite covolume* if the volume of a Dirichlet domain is finite. (See ideal triangle groups)
- This is well-defined.
- If A Kleinian group Γ is of finite covolume, then if Γ is geometrically finite and hence finitely generated. (finitely presented) (Converse not true)
- This has a rather involved proof....

5 Hyperbolic manifolds and orbifolds

Metric structures of hyperbolic manifolds in general

- Margulis constant $\epsilon > 0$.
- Given a hyperbolic manifold M , $M = \mathbb{H}^3/\Gamma$ for a torsion-free Γ , the set of thin parts is defined as $M_\epsilon = \{x \in \mathbb{H}^3/\Gamma \mid \exists x_1, x_2 \in x, d(x_1, x_2) \leq \epsilon\}$.
- The thick part is defined as $M_0 = \{x \in \mathbb{H}^3/\Gamma \mid \forall x_1, x_2 \in x, d(x_1, x_2) > \epsilon\}$.
- The thin part either an annulus, a Mobius band, a torus or a Klein bottle times interval (corresponds to cusps) or is a solid torus or solid Klein bottle.
- The thick part is a tame 3-manifold, i.e., either is compact or is the interior of a compact 3-manifold. (Hence, the topology is finite.)
- The orbifold versions are similar to this..(that is the thin parts are finite quotients of the above.)
- These work for general geometric manifolds...

Commensurability

- Γ_1, Γ_2 subgroups of $\text{PSL}(2, \mathbb{C})$. They are *directly commensurable* if $\Gamma_1 \cap \Gamma_2$ is of finite index in both Γ_1 and Γ_2 .
- They are *commensurable* if Γ_1 and a conjugate of Γ_2 are directly commensurable.
- Two hyperbolic orbifolds \mathbb{H}^3/Γ_1 and \mathbb{H}^3/Γ_2 are commensurable if their groups are so.
- Examples: Consider subgroups of a common Kleinian group.