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# On the classification of positive quaternionic Kähler manifolds with $b_{4}=1$ 

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#### Abstract

Let $M$ be a positive quaternionic Kähler manifold of dimension $4 m$. We already showed that if the symmetry rank is greater than or equal to $\left[\frac{m}{2}\right]+2$ and the fourth Betti number $b_{4}$ is equal to one, then $M$ is isometric to $\mathbb{H} P^{m}$. The goal of this paper is to report that we can improve the lower bound of the symmetry rank by one for higher even dimensional positive quaternionic Kähler manifolds. Namely, it is shown in this paper that if the symmetry rank of $M$ with $b_{4}(M)=1$ is greater than or equal to $\frac{m}{2}+1$ for $m \geq 10$, then $M$ is isometric to $\mathbb{H} P^{m}$. One of the main strategies of this paper is to apply a more delicate argument of Frankel type to positive quaternionic Kähler manifolds with certain symmetry rank.


## 1 Introduction and Main Results

A compact quaternionic Kähler manifold $M$ is a Riemannian manifold of real dimension $4 m$ whose holonomy group is contained in the Lie group $\operatorname{Sp}(m) \operatorname{Sp}(1)=$ $\mathrm{Sp}(m) \times \mathrm{Sp}(1) / \mathbf{Z}_{2}$ in $\mathrm{SO}(4 m)$ for $m \geq 2$. Such a manifold is called positive if it has the positive scalar curvature. It is known that every quaternionic Kähler manifold is simply connected and Einstein. Moreover, it is easy to see from a well-known theorem of Meyers that every positive quaternionic Kähler manifold is compact. It is common to define a 4 -dimensional quaternionic Kähler manifold to be both Einstein with non-zero scalar curvature and self-dual. While many complete, non-compact, non-symmetric quaternionic Kähler manifolds with negative scalar curvature are known to exist, so far the only known examples of positive (compact) quaternionic Kähler manifolds are the so-called

[^0]Wolf spaces: Wolf proved that for each compact simple Lie group $G$, there is a symmetric space $G / H$. For examples, the classical ones are

$$
\begin{aligned}
\mathbb{H} P^{m} & =\frac{\mathrm{Sp}(m+1)}{\mathrm{Sp}(m) \times \mathrm{Sp}(1)}, \\
G r_{2}\left(\mathbb{C}^{m+2}\right) & =\frac{\mathrm{SU}(m+2)}{S(\mathrm{U}(m) \times \mathrm{U}(2))}, \\
G \widetilde{\left(\mathbb{R}^{m+4}\right)} & =\frac{\mathrm{SO}(m+4)}{S(\mathrm{O}(m) \times \mathrm{O}(4))},
\end{aligned}
$$

and there are five more exceptional cases. Moreover, a theorem of Alekseevsky asserts that there are no other compact homogeneous positive quaternionic Kähler manifolds (e.g., see [1]).

Quite recently, in the paper [10] R. Kobayashi and K. Onda announced a proof of the LeBrun-Salamon conjecture saying that every irreducible positive quaternioinic Kähler manifold is isometric to one of the Wolf spaces. Their proof crucially uses the Ricci flow technique developed by G. Perelman, S. Bando and W. X. Shi (see [12], [2] and [15]).

Every positive quaternionic Kähler manifold admits a twistor space which is a complex contact Fano manifold. It is also true that a contact Fano manifold is a twistor space of a positive quaternionic Kähler manifold if and only if it admits a Kähler-Einstein metric. However, it is generally believed that every contact Fano manifold admits a Kähler-Einstein manifold. In view of the recent result of Kobayashi-Onda and Wolf, it seems to be reasonable to conjecture that every contact Fano manifold with the second Betti number $b_{2}=1$ is indeed a symmetric space.

In this paper, we take a quite different approach to classify positive quaternionic Kähler manifolds, which is likely to contain much weaker, but more geometric and so meaningful, results than those of Kobayashi and Onda. In other words, we exclusively consider positive quaternionic Kähler manifolds with an isometry group of certain rank. For instance, it is known in [14] that every 16dimensional positive quaternionic Kähler manifold admits an isometry group of dimension 8. Hence such a manifold admits an isometric torus action of rank at least 2 .

In the papers [4] and [5], Fang showed that for $m$ even integer every positive quaternionic Kähler $4 m$-manifold with $\operatorname{sym}-\operatorname{rank}(M) \geq \frac{m}{2}+3$ is isometric to $\mathbb{H} P^{m}$ or $G r_{2}\left(\mathbb{C}^{m+2}\right)$. (Here the symmetry rank sym-rank $(M, g)$ (or simply sym-rank $(M)$ ) of a Riemannian manifold with a Riemannian metric $g$ is defined as the rank of the isometry group $\operatorname{Isom}(M, g)$. Equivalently, it can be defined as the largest number $r$ such that a $r$-dimensional torus acts effectively and isometrically on $M$ ). Moreover, the first named author showed in [8] that every positive quaternionic Kähler $4 m$-manifold with $\operatorname{sym}-\operatorname{rank}(M) \geq\left[\frac{m}{2}\right]+3$ is isometric to $\mathbb{H} P^{m}$ or $G r_{2}\left(\mathbb{C}^{m+2}\right)$, regardless of the parity of the integer $m$. One of the crucial arguments in the proof is an extended version of connectedness theorem in [4] in the presence of the group action. Recently, in the paper [9] we were able to improve the lower bound of the paper [8] further by one under
the assumption of the fourth Betti number $b_{4}=1$ by applying more delicate arguments. On the other hands, the classification of low dimensional positive quaternionic Kähler manifolds has already been done by N. Hitchin, Poon and Salamon, Herrera and Herrera (see [7], [13] and [6] for more details).

The aim of this paper is to give a classification result of positive quaternionic Kähler manifolds satisfying both the fourth Betti number $b_{4}(M)=1$ and sym$\operatorname{rank}(M) \geq \frac{m}{2}+1$. Our first main result is

Theorem 1.1. Let $M$ be a positive quaternionic Kähler manifold of dimension $4 m$ with an isometric $T^{k}$-action. If $k$ is greater than or equal to 6 , then the dimension of any fixed point component of the $S^{1}$-action induced from the $T^{k}$ action is greater than or equal to $4 k$.

We will prove Theorem 1.1 by contradiction, in Section 2. Namely, otherwise we would find two fixed point components under the induced $T^{k-3}$-action. Then let $\gamma$ denote a minimizing geodesic joining between two fixed point components, and use the second variation of $\gamma$. Since every positive quaternionic Kähler manifold has a positive scalar curvature of $M$, we can derive a contradiction to Proposition 1.2 in [4]. (See Section 2 for more details.)

Our second main result is
Theorem 1.2. Let $M$ be a positive quaternionic Kähler manifold of dimension $4 m$ with $b_{4}(M)=1$. If the symmetry rank satisfies $\operatorname{sym}-\operatorname{rank}(M) \geq \frac{m}{2}+1$ for $m \geq 10$, then $M$ is isometric to $\mathbb{H} P^{m}$.

This theorem is actually a corollary of Theorem 1.1. We will prove it by using a mathematical induction starting from the case $m=10$. The restriction on the dimension in Theorem 1.2 might be improved or removed, but to do so we probably need new insights or techniques. So we hope to return this issue in a future paper. Along the proof of Theorem 1.2. the following rigidity theorem of LeBrun and Salamon will be crucially used.

Theorem 1.3 ([11]). The second homotopy group $\pi_{2}(M)$ of a positive quaternionic Kähler manifold $M$ is a finite group with 2-torsion or $\mathbb{Z}$, and $M$ is isometric to $\mathbb{H} P^{n}$ or $G r_{2}\left(\mathbb{C}^{n+2}\right)$, according to $\pi_{2}(M)=0$ or $\mathbb{Z}$.

We also need the following connectedness theorem whose statement without the presence of a group action is due to Fang in [4]:

Theorem 1.4 ([8]). Let $M$ be a positive quaternionic Kähler manifold of dimension $4 m$. If $N$ is a quaternionic Kähler submanifold of dimension $4 n$, then the inclusion $N \hookrightarrow M$ is $(2 n-m+1)$-connected. Furthermore, if there is a Lie group $G$ acting isometrically on $M$ and fixing $N$ pointwise, then the inclusion map is $(2 n-m+1+\delta(G))$-connected, where $\delta(G)$ is the dimension of the principal orbit of $G$.

We organize this paper as follows. In Section 2, we give a proof of Theorem 1.1 which is one of the key ingredients to prove Theorem 1.2. In order to prove Theorem 1.2, we use the mathematical induction on the dimension of a
positive quaternionic Kähler manifold with certain symmetry rank. To do so, we need to deal with a positive quaternionic Kähler manifold of dimension 40 with an isometric $T^{6}$-action, and Section 3 is devoted to the classification of such manifolds. Finally, in Section 4 we give a proof of our main Theorem 1.2 which will be based on the classification of a positive quaternionic Kähler manifold of dimension 40 with an isometric $T^{6}$-action established in Section 3.

## 2 Proof of Theorem 1.1

In this section we give a proof of Theorem 1.1 which will play a crucial role in the proof of Theorem 1.2. To do so, as before let $M$ be a positive quaternionic Kähler manifold of dimension $4 m$. Assume that $M$ admits an isometric $T^{k}$ action. Let $V$ denote a fixed point component of the $S^{1}$-action induced from the $T^{k}$-action.

We begin with this section by setting up some notations for later use. When $T^{i}$ acts on $M$, we denote by $\operatorname{Fix}\left(T^{i}, M\right)$ the fixed point set of $T^{i}$-action. One of the connected components of $\operatorname{Fix}\left(T^{i}, M\right)$ will be often denoted by $\operatorname{Fix}\left(T^{i}, M\right)_{0}$. We shall also denote by $N_{i}$ one of the connected components of $\operatorname{Fix}\left(T^{i}, M\right)$, and $d_{i}$ will always mean its dimension. With these notations in place, note that we can choose $N_{i+1}$ in $\operatorname{Fix}\left(S^{1}, N_{i}\right) \subset \operatorname{Fix}\left(T^{i+1}, M\right)$. Thus one can consider the following chain at $x$ :

$$
x \in N_{k} \subset N_{k-1} \subset \cdots \subset N_{1} \subset M
$$

Therefore, from now on we will always assume without further mentioning that there is the relation $N_{i} \subset N_{i-1} \subset M$ for $2 \leq i \leq k$.

As mentioned in Section 1, we prove Theorem 1.1 by contradiction. Hence suppose that $V$ has the dimension less than or equal to $4 k-4$. Note that, since $V$ admits $T^{k-1}$-action by its construction, it follows from Theorem B in [4] that the dimension of $V$ should be greater than or equal to $4 k-8$. Then we claim the following lemma.

Lemma 2.1. There exist two fixed-point components contained in $V$ under the $T^{k-3}$-action induced from the $T^{k-1}$-action on $V(k \geq 6)$.

Proof. We divide the proof into two cases:
Case 1: Assume first that the dimension of $V$ is equal to $4 k-4$.
For the sake of simplicity, let $N_{0}=V$. Then, for each $0 \leq i \leq k-2$, we can define a fixed-point component $N_{i}$ inductively in such a way that $N_{i+1}=$ $\operatorname{Fix}\left(S^{1}, N_{i}\right)_{0}$. So clearly we have the following inclusions:

$$
V=N_{0} \supset N_{1} \supset \cdots \supset N_{k-1} .
$$

In particular, note that $N_{k-3}$ admits an isometric $T^{2}$-action. Thus we have $\operatorname{dim}\left(N_{k-3}\right) \geq 4$ by Theorem B in [4]. Moreover, we have $\operatorname{dim}\left(N_{k-3}\right) \leq$ $\operatorname{dim}\left(N_{0}\right)-4(k-3)=(4 k-4)-4(k-3)=8$ in this case.

If $\operatorname{dim}\left(N_{k-3}\right)=8$ then $\operatorname{dim}\left(N_{k-4}\right)=12$ by the effectiveness of the isometric action. Then it follows from Theorem 1.2 in [5] that $N_{k-4}$ should be isometric to $\mathbb{H} P^{3}$ or $G r_{2}\left(\mathbb{C}^{5}\right)$.

Now note that $\operatorname{dim}\left(N_{i}\right)-\operatorname{dim}\left(N_{i+1}\right)=4$ for $0 \leq i \leq k-5$. Let $d_{i}=\operatorname{dim} N_{i}$. Then it is easy to see that

$$
2+d_{i+1} / 2-d_{i} / 4=2+d_{i+1} / 2-\left(d_{i+1}+4\right) / 4=1+d_{i+1} / 4 \geq 3
$$

since $d_{i+1} \geq 12$. Thus we have

$$
\pi_{2}(V)=\pi_{2}\left(N_{1}\right)=\ldots=\pi_{2}\left(N_{k-4}\right)
$$

This implies that V is actually isometric to $\mathbb{H} P^{k-1}$ or $G r_{2}\left(\mathbb{C}^{k+1}\right)$.
Next assume that $\operatorname{dim}\left(N_{k-3}\right)=4$. If $\operatorname{dim}\left(N_{1}\right)=4 k-8$, then by Theorem 1.2 in [5], $V$ is isometric to $\mathbb{H} P^{k-1}$ or $G r_{2}\left(\mathbb{C}^{k+1}\right)$.

If $\operatorname{dim}\left(N_{1}\right)=4 k-12, N_{1}$ admits the maximal symmetry rank. Note that $\operatorname{dim}\left(N_{i}\right)=4 k-8-4 i$ for $1 \leq i \leq k-3$. Hence $\operatorname{dim}\left(N_{1}\right)-\operatorname{dim}\left(N_{2}\right)=4$. Again by Theorem 1.2 in [5] and $4 k-12 \geq 12(k \geq 6), N_{1}$ is isometric to $\mathbb{H} P^{k-3}$ or $G r_{2}\left(\mathbb{C}^{k-1}\right)$. Since

$$
1 / 2(4 k-12)-1 / 4(4 k-4)+2 \geq k-3 \geq 3
$$

(i.e., $N_{1} \rightarrow V$ is at least 3 -connected), $V$ is isometric to $\mathbb{H} P^{k-1}$ or $G r_{2}\left(\mathbb{C}^{k+1}\right)$. Now we are ready to consider the following subcases in more detail:
Subcase 1.1: $V$ is isometric to $\mathbb{H} P^{k-1}$.
Note that the Euler characteristic $\chi(V)=k$ of $V$ is greater than or equal to 6 , since $k \geq 6$. If $\operatorname{dim}\left(N_{k-3}\right)=8, N_{k-3}$ is isometric to $\mathbb{H} P^{2}$. Thus $\chi\left(N_{k-3}\right)=3$.

Similarly, for the case of $\operatorname{dim}\left(N_{k-3}\right)=4$, by Hitchin in [7], $N_{k-3}$ is $S^{4}$ or $\mathbb{C} P^{2}$. Thus $\chi\left(N_{k-3}\right) \leq 3$. Notice that $\operatorname{dim}\left(\operatorname{Fix}\left(T^{2}, N_{k-3}\right)\right)$ is less than or equal to 4 , due to the conditions of $\operatorname{dim}\left(N_{k-3}\right) \leq 8$ and the existence of an isometric $T^{2}$-action on $N_{k-3}$.

For $i=1,2$, let $W_{i}$ denote the fixed point components of dimension 4 under the $T^{k-1}$-action on $V$. Since the Euler characteristic $\chi(V)$ of $V$ is greater than or equal to 6 , we can consider the following three possibilities: either $\operatorname{Fix}\left(T^{k-1}, V\right)$ contains six isolated fixed points $x_{1}, \ldots, x_{6}$ or three isolated fixed points $x_{1}, x_{2}, x_{3}$ and $W_{1}$ or the union $W_{1} \cup W_{2}$.

Assume first that $\operatorname{Fix}\left(T^{k-1}, V\right)$ contains six isolated fixed points $x_{1}, \ldots, x_{6}$. Let

$$
T^{k-1}=S_{1}^{1} \times S_{2}^{1} \times \cdots \times S_{k-1}^{1}
$$

where $S_{j}^{1}(1 \leq j \leq k-1)$ is the unit circle group. Then, by considering the isotropy representation at $x_{1}$ of the $T^{k-1}$-action, we can choose $K_{1}$ to be $\operatorname{Fix}\left(T^{k-1} /\left(S_{1}^{1} \times S_{2}^{1}\right), V\right)_{0}$ containing the isolated fixed point $x_{1}$. Since $\chi\left(K_{1}\right) \leq 3$, we may assume without loss of generality that $\operatorname{Fix}\left(S_{1}^{1} \times S_{2}^{1}, K_{1}\right) \backslash\left\{x_{1}, x_{2}, x_{3}\right\}=\emptyset$. Note that there exists no fixed point component of dimension 2.

Similarly, by considering the isotropy representation of the $T^{k-1}$-action at $x_{4}$, we can choose another fixed point component $K_{2}$ to be $\operatorname{Fix}\left(T^{k-1} /\left(S_{1}^{1} \times\right.\right.$
$\left.\left.S_{2}^{1}\right), V\right)_{0}$ containing the isolated fixed point $x_{4}$. We then claim that $K_{1} \cap K_{2}$ is empty. Indeed, otherwise then $K_{1}$ should coincide with $K_{2}$. But then $K_{1}$ would contain $x_{4}$, which is clearly a contradiction. Similar arguments apply to other two cases. Therefore we have completed the proof of Lemma 2.1 in this Subcase 1.1.

Subcase 1.2: $V$ is isometric to $G r_{2}\left(\mathbb{C}^{k+1}\right)$.
Let $m=k-1$. It is well-known that

$$
\begin{equation*}
\chi\left(G r_{2}\left(\mathbb{C}^{m+2}\right)\right)=(m+2)(m+1) / 2 \tag{2.1}
\end{equation*}
$$

If $\operatorname{dim}\left(N_{k-3}\right)=8$, then $\chi\left(N_{k-3}\right) \leq 6$. On the other hands, if $\operatorname{dim}\left(N_{k-3}\right)=4$, then by Hitchin $([7]), N_{k-3}=\mathbb{C} P^{2}$ or $S^{4}$ and so $\chi\left(N_{k-3}\right) \leq 3$. Thus we always have $\chi\left(N_{k-3}\right) \leq 6$. Since $k \geq 6, \chi\left(G r_{2}\left(\mathbb{C}^{k+1}\right)\right)=(k+1) k / 2 \geq 21$.

Without a loss of generality, we let $K_{1}=N_{k-3}=\operatorname{Fix}\left(T^{k-1} /\left(S_{1}^{1} \times S_{2}^{1}\right), V\right)_{0}$. Since $\chi\left(K_{1}\right) \leq 6$ and $\chi(V) \geq 21$, there exists an $x_{4} \in \operatorname{Fix}\left(T^{k-1}, V \backslash K_{1}\right)$. Consider the fixed point component $K_{2}=\operatorname{Fix}\left(T^{k-1} /\left(S_{1}^{1} \times S_{2}^{1}\right), V\right)_{0}$ containing $x_{4}$. Then we have $K_{1} \cap K_{2}=\emptyset$.

Case 2: Assume next that the dimension of $V$ is equal to $4 k-8(\geq 16)$.
Observe that the fixed point set for the $T^{k-1}$-action is isolated. We can assume that

$$
T^{k-1}=S_{0}^{1} \times \ldots \times S_{k-2}^{1}
$$

where $S_{l}^{1}(0 \leq l \leq k-2)$ is the unit circle group.
At $x \in \operatorname{Fix}\left(T^{k-1}, V\right)$, we can assume that $T^{k-2}=T^{k-1} / S_{0}^{1}$ acts left quaternionically linearly on $T_{x}(V)$.

Let $N_{l}=\operatorname{Fix}\left(S_{1}^{1} \times \ldots \times S_{l}^{1}, V\right)_{0}$. Then $\operatorname{dim}\left(N_{l}\right)=4 k-8-4 l$. Assume that $\operatorname{Fix}\left(T^{k-1}, V\right)$ consists of $x_{1}, x_{2}, x_{3}, \ldots$. Let $K_{1}=\operatorname{Fix}\left(S_{1}^{1} \times \ldots \times S_{k-3}^{1}, V\right)_{0} \ni x_{1}$. Since $\chi\left(K_{1}\right) \leq 3, \operatorname{Fix}\left(S_{0}^{1} \times S_{k-2}^{1}, K_{1}\right) \backslash\left\{x_{1}, x_{2}, x_{3}\right\}=\emptyset$. Let $K_{2}=\operatorname{Fix}\left(S_{1}^{1} \times \ldots \times\right.$ $\left.S_{k-3}^{1}, V\right)_{0} \ni x_{4}$. Then $K_{1} \cap K_{2}=\emptyset$.

This completes the proof of Lemma 2.1.
Now we are ready to prove Theorem 1.1. By Lemma 2.1, we can take two disjoint totally geodesic submanifolds $K_{1}$ and $K_{2}$ in $\operatorname{Fix}\left(T^{k-3}, V\right)$ whose dimension satisfies $4 \leq \operatorname{dim} K_{i} \leq 8$ for $i=1,2$. Let $L=K_{1} \times K_{2}, f_{i}: K_{i} \rightarrow V$ the quaternionic immersions for each $i=1,2$, and $f=\left(f_{1}, f_{2}\right)$. Let $s$ be the distance between $K_{1}$ and $K_{2}$ and let $\gamma:[0, s] \rightarrow V$ be a minimizing geodesic from $K_{1}$ to $K_{2}$.

Let $\mathcal{V}$ be the real linear vector space spanned by vectors $(W(0), W(1))$, where $W$ is a parallel vector field along $\gamma$ so that $W$ is orthogonal to $\dot{\gamma}, I \dot{\gamma}, J \dot{\gamma}$, and $K \dot{\gamma}$. Then the quaternionic dimension of $\mathcal{V}$ is equal to $\operatorname{dim}_{\mathbb{H}}(V)-1$. Notice that $I W$ as well as $J W$ and $K W$ is orthogonal to all of $\dot{\gamma}, I \dot{\gamma}, J \dot{\gamma}$, and $K \dot{\gamma}$. This implies that $(I W(0), I W(1)),(J W(0), J W(1))$, and $(K W(0), K W(1))$ are actually in $\mathcal{V}$.

Lemma 2.2.

$$
\operatorname{dim}_{\mathbb{H}}\left(\mathcal{V} \cap f_{*}\left(T_{(\gamma(0)=x, \gamma(s)=y)} L\right)\right) \geq 1
$$

Proof. For the sake of simplicity, let $G=T^{k-3}$.
We first consider the case that $\operatorname{dim} V=4 k-4$ and $\operatorname{dim} K_{1}=\operatorname{dim} K_{2}=4$. Suppose on the contrary that $\operatorname{dim}_{\mathbb{H}}\left(\mathcal{V} \cap f_{*}\left(T_{(x, y)} L\right)\right)=0$. Let $v_{1}$ be a unit vector in the tangent space of $\left(K_{1}\right)_{\gamma(0)}, P$ a parallel transport from $\gamma(0)$ to $\gamma(s)$ along $\gamma$, and $v$ the parallel vector field along $\gamma$ such that $v(0)=v_{1}$. Then, by assumption, $v(s)=P\left(v_{1}\right)$ is in the normal space $\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp}$ of the tangent space $\left(K_{2}\right)_{\gamma(s)}$.

Since $G$ acts on $\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp} \backslash\{0\}$ fixed-point freely, there must exist $g \neq 1 \in$ $G$ such that $d g\left(P\left(v_{1}\right)\right) \neq P\left(v_{1}\right)$, so that $\left\langle d g\left(P\left(v_{1}\right)\right), P\left(v_{1}\right)\right\rangle<\left\|P\left(v_{1}\right)\right\|^{2}$. Since $P$ is an isometry and $v(0)$ is a tangent vector of $K_{1}$ fixed by the group action of $G$, we have

$$
\begin{aligned}
1 & =\left\|v_{1}\right\|_{\gamma(0)}^{2}=\left\langle d g\left(v_{1}\right), v_{1}\right\rangle_{\gamma(0)}=\left\langle P\left(d g\left(v_{1}\right)\right), P\left(v_{1}\right)\right\rangle_{\gamma(s)} \\
& =\left\langle d g\left(P\left(v_{1}\right)\right), P\left(v_{1}\right)\right\rangle_{\gamma(s)}<\left\|P\left(v_{1}\right)\right\|^{2}=1,
\end{aligned}
$$

which is a contradiction. Hence $\mathcal{V}$ has at least quaternionic dimension 1.
Next we deal with the case that $\operatorname{dim} K_{1}=8$ and $\operatorname{dim} K_{2}=4$. Again suppose that $\operatorname{dim}_{\mathbb{H}}\left(\mathcal{V} \cap f_{*}\left(T_{(x, y)} L\right)\right)=0$. Then notice that any vector in $\left(K_{1}\right)_{\gamma(0)}$ is transported to $\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp}$ and that any vector in $\left(K_{1}\right)_{\gamma(0)}$ is transported to $\operatorname{Fix}\left(G,\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp}\right)$. Thus $V_{\gamma(s)}$ contains

$$
P\left(\left(K_{1}\right)_{\gamma(0)}\right) \oplus\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp} \backslash \operatorname{Fix}\left(G,\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp}\right) \oplus\left(K_{2}\right)_{\gamma(s)}
$$

Notice that $G$ acts on $\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp} \backslash \operatorname{Fix}\left(G,\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp}\right)$ nontrivially. Since

$$
\begin{align*}
& \operatorname{dim}_{\mathbb{H}}\left(P\left(\left(K_{1}\right)_{\gamma(0)}\right)+\operatorname{dim}_{\mathbb{H}}\left(\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp} \backslash \operatorname{Fix}\left(G,\left(\left(K_{2}\right)_{\gamma(s)}\right)^{\perp}\right)\right)+\right.  \tag{2.2}\\
& \operatorname{dim}_{\mathbb{H}}\left(\left(K_{2}\right)_{\gamma(s)}\right) \geq \operatorname{dim}_{\mathbb{H}} K_{1}+\operatorname{dim} G+\operatorname{dim}_{\mathbb{H}} K_{2}=k,
\end{align*}
$$

and $\operatorname{dim}_{\mathbb{H}} V=k-1$, this is a contradiction. That is, $\mathcal{V}$ has at least quaternionic dimension 1.
If $\operatorname{dim} V=4 k-4$ and $\operatorname{dim} K_{1}=\operatorname{dim} K_{2}=8$, we will prove by similar process in the above case (cf. (2.2)).

$$
\operatorname{dim} V_{\gamma(s)} \geq \operatorname{dim}_{\mathbb{H}} K_{1}+\operatorname{dim} G+\operatorname{dim}_{\mathbb{H}} K_{2}=2+(k-3)+2=k+1
$$

It is a contradiction. That is, $\mathcal{V}$ has at least quaternionic dimension 1.
Finally, if $\operatorname{dim} V=4 k-8, \operatorname{dim} K_{1}=4$, and $\operatorname{dim} K_{2} \geq 4$, then this time we have

$$
\operatorname{dim} G+\operatorname{dim}_{\mathbb{H}} K_{1}+\operatorname{dim}_{\mathbb{H}} K_{2} \geq k-1
$$

It is again a contradiction since $\operatorname{dim}_{\mathbb{H}} V=k-2$. Thus $\mathcal{V}$ has at least quaternionic dimension 1.

This completes the proof of Lemma 2.2.
By Lemma 2.2, there exists a parallel field $X$ along $\gamma$. Since $K_{1}$ and $K_{2}$ are
positive quaternionic Kähler manifolds by a theorem of Berger in [3], we have

$$
\begin{align*}
& L_{X}^{\prime \prime}(0)+L_{I X}^{\prime \prime}(0)+L_{J X}^{\prime \prime}(0)+L_{K X}^{\prime \prime}(0)=-\int_{0}^{s}\langle R(T, X) T, X\rangle \\
& +\langle R(T, I X) T, I X\rangle+\langle R(T, J X) T, J X\rangle+\langle R(T, K X) T, K X\rangle d t  \tag{2.3}\\
& =-\int_{0}^{s} \frac{\lambda}{n+2}\|T\|^{2}\|X\|^{2} d t<0,
\end{align*}
$$

where $\lambda>0$ is Einstein constant and $T=\gamma^{\prime}(t)$. Since $\gamma$ is minimizing, it is a contradiction. This proves Theorem 1.1.

## 3 Positive quaternionic Kähler manifolds of dimension 40

The aim of this section is to classify positive quaternionic Kähler manifolds of dimension 40 which admits an isometric $T^{6}$-action. We need to consider this case in detail in order to apply the mathematical induction.

Throughout this section, let $M$ be a positive quaternionic Kähler manifold of dimension 40 with an isometric $T^{6}$-action. By Theorem 0.3 in [11], all odd Betti numbers are equal to zero. Thus $\chi(M)>0$, so there exist $x \in \operatorname{Fix}\left(T^{6}, M\right)_{0}$.

Consider the following chain at $x\left(\in N_{6}\right)$ :

$$
M \supset N_{1} \supset \cdots \supset N_{5} \supset N_{6}
$$

and let $d_{i}$ denote the dimension of $N_{i}$ for $1 \leq i \leq 6$, as before. By the representation $T^{6} \rightarrow \mathrm{Sp}(n)_{x} \mathrm{Sp}(1)_{x}$, there exists subgroup $T^{5}$ such that $T^{5}$ acts left quaternionically linearly (cf. 7 page in [4]). Thus without loss of generality we can assume that $N_{1}$ admits $T^{5}$-action acting left quaternionically linearly at $x$.

Then we have the following lemma.
Lemma 3.1. The following three cases of 6-tuples $\left(d_{1}, d_{2}, d_{3}, d_{4}, d_{5}, d_{6}\right)$ do not occur:

$$
(32,24,16,8,4,0),(32,24,12,8,4,0),(32,16,12,8,4,0) .
$$

Proof. Suppose not. Then, the fixed point set should be isolated. In this proof, we will use the Euler characteristic of $N_{3}$.
Case 1: Assume that $\left(d_{1}, d_{2}, d_{3}, d_{4}, d_{5}, d_{6}\right)=(32,24,16,8,4,0)$. Then we claim that $\chi\left(N_{3}\right) \geq 6$. If $b_{2}\left(N_{3}\right)=1, N_{3}$ is isometric to $G r_{2}\left(\mathbb{C}^{6}\right)$ and thus $\chi\left(N_{3}\right) \geq 6$.

Recall that by a theorem of Salamon in [14] we have the following formula:

$$
\begin{equation*}
3 b_{4}=b_{6}+2 b_{8}+1 \tag{3.1}
\end{equation*}
$$

where $b_{2}\left(N_{3}\right)=0$. From (3.1), $b_{4}\left(N_{3}\right) \geq 1$. If $b_{6}\left(N_{3}\right)=b_{8}\left(N_{3}\right)=0$, it is a contradiction from (3.1). Thus $b_{6}\left(N_{3}\right)+b_{8}\left(N_{3}\right) \geq 1$. Thus $\chi\left(N_{3}\right)=2+$ $2\left(b_{4}\left(N_{3}\right)+b_{6}\left(N_{3}\right)+b_{8}\left(N_{3}\right)\right) \geq 6$. This prove the claim.

Set $T^{6}=S_{1}^{1} \times \ldots \times S_{6}^{1}$ and let $N_{3}=\operatorname{Fix}\left(S_{4}^{1} \times S_{5}^{1} \times S_{6}^{1}, M\right)_{0}$. Then, by the assumption, $\operatorname{Fix}\left(S_{1}^{1} \times S_{2}^{1} \times S_{3}^{1}, N_{3}\right)$ is isolated. So we may assume that

$$
\operatorname{Fix}\left(S_{1}^{1} \times S_{2}^{1} \times S_{3}^{1}, N_{3}\right) \supseteq\left\{x_{1}, \ldots, x_{4}\right\}
$$

Now, let $C_{1}$ be $\operatorname{Fix}\left(T^{6} / S_{1}^{1}, M\right)_{0}$ containing $x_{1}$. Since $\operatorname{dim} C_{1}=4$, we have $\chi\left(C_{1}\right) \leq 3$ by $[7]$. So we may assume that $\operatorname{Fix}\left(S_{1}^{1}, C_{1}\right) \backslash\left\{x_{1}, x_{2}, x_{3}\right\}=\emptyset$. Let $C_{4}$ be $\operatorname{Fix}\left(S_{2}^{1} \times S_{3}^{1}, N_{3}\right)_{0}$ containing $x_{4}$. Note that by the definition of a fixed point component, $C_{1} \cap C_{4}=\emptyset$. Note also that by construction $\operatorname{Fix}\left(S_{2}^{1} \times S_{3}^{1}, N_{3}\right) \supset$ $C_{1} \cup C_{4}$. Recall that $\operatorname{dim} C_{4}=4$ by assumption.

Let $\gamma$ be a minimizing geodesic from $C_{1}$ to $C_{4}$ such that $\gamma(0)=p \in C_{1}$ and $\gamma(l)=q \in C_{4}$ where $l$ is the distance from $C_{1}$ to $C_{4}$. Note that $S_{2}^{1} \times S_{3}^{1}$ acts on $\left(C_{4}\right)_{q}^{\perp} \backslash\{0\}$ fixed-point freely.

Let $P$ denote the parallel transport from $p$ to $q$ along $\gamma$. Then we claim that for some $v \neq 0 \in\left(C_{1}\right)_{p}, P(v) \in\left(C_{4}\right)_{q}$. To see it, suppose on the contrary that for any $v \neq 0 \in\left(C_{1}\right)_{p}$ such that $\|v\|=1, P(v) \in\left(C_{4}\right)_{q}^{\perp}$. Clearly there exists $g \in S_{2}^{1} \times S_{3}^{1}$ such that $g \cdot P(v) \neq P(v)$. Then apply an argument as in the previous section. That is, we have

$$
\begin{aligned}
1 & =\|v\|^{2}=\langle g \cdot v, v\rangle=\langle P(g \cdot v), P(v)\rangle \\
& =\langle g \cdot P(v), P(v)\rangle<\|P(v)\|^{2}=1 .
\end{aligned}
$$

It is a contradiction. This proves the claim. Let $X$ be a parallel vector field along $\gamma$ such that $X(0)=v \in\left(C_{1}\right)_{p}$ and $X(l) \in\left(C_{4}\right)_{q}$.

Finally, we have

$$
L_{X}^{\prime \prime}(0)+L_{I X}^{\prime \prime}(0)+L_{J X}^{\prime \prime}(0)+L_{K X}^{\prime \prime}(0)<0
$$

(cf. (2.3) in Section 2) Since $\gamma$ is minimizing, it is a contradiction.
Case 2: Assume that $\left(d_{1}, d_{2}, d_{3}, d_{4}, d_{5}, d_{6}\right)=(32,24,12,8,4,0)$ or $(32,16,12,8,4,0)$. Since $d_{3}-d_{4}=4$, by Theorem 1.2 in [5], $N_{3}$ is isometric to $\mathbb{H} P^{3}$ or $G r_{2}\left(\mathbb{C}^{5}\right)$. Thus $\chi\left(N_{3}\right) \geq 4$. The rest of the proof is completely similar to Case 1. So we leave it to the reader. This completes the proof of Lemma 3.1.

Recall that an isometric $G$-action on a quaternionic Kähler manifold $M$ is called of quaternionic type if $\bar{\rho}_{x}: G \rightarrow \operatorname{Sp}(1)_{x}$ is trivial for any $G$-fixed point point $x$.

Theorem 3.2. Let $M$ be a positive quaternionic Kähler manifold of dimension 40 with an isometric $T^{6}$-action. If $b_{4}(M)$ is equal to 1 , then $M$ is isometric to $\mathbb{H} P^{10}$.

Proof. $\chi(M)>0$. Thus $\operatorname{Fix}\left(T^{6}, M\right) \ni x$. Since $M$ admits an isometric $T^{6}$ action, we may assume that at least $T^{5}$ acts left quaternionically linearly on $T_{x}(M)$. Especially, we can assume that $T^{5}$ acts left quaternionically linearly on $T_{x}\left(N_{1}\right)$ where $N_{1}=\operatorname{Fix}\left(S^{1}, M\right)_{0}$. If $N_{i}=\operatorname{Fix}\left(T^{i}, M\right)_{0}$, Consider a chain at $x$ :

$$
N_{1} \supseteq N_{2} \supseteq N_{3} \ni x .
$$

Notice that by Theorem $1.1 d_{1}$ should be greater than or equal to 24 . Now we consider all possible dimensions which the submanifold $N_{1}$ can have.

If $d_{1}=36$, by Theorem 1.2 in [4], $M$ is isometric to $\mathbb{H} P^{10}$ or $G r_{2}\left(\mathbb{C}^{12}\right)$. Since $b_{4}\left(G r_{2}\left(\mathbb{C}^{12}\right)\right)>1, M$ is isometric to $\mathbb{H} P^{10}$. On the other hands, Consider the case $\left(d_{1}, d_{2}\right)=(32,20)$. Since $N_{3}$ admits an isometric $T^{3}$ acting quaternionically linearly on $T_{x}\left(N_{3}\right), d_{3} \geq 12$. Thus for $\left(d_{1}, d_{2}, d_{3}, d_{4}\right)=(32,20,12,8)$ (resp. $\left.\left(28,20,16, d_{4}\right)\right)$, it follows from Theorem 1.2 in [4] that $N_{3}\left(\right.$ resp. $\left.N_{2}\right)$ is isometric to quaternionic Kähler space or complex Grassmannian space, since $d_{3}-d_{4}=4$ (resp. $d_{2}-d_{3}=4$ ). By Theorem 1.4, we have $\pi_{2}\left(N_{3}\right)=\pi_{2}(M)\left(\right.$ resp. $\pi_{2}\left(N_{2}\right)=$ $\left.\pi_{2}(M)\right)$. Thus $M$ is isometric to $\mathbb{H} P^{10}$, since $b_{4}(M)=1$.

The proof of other remaining cases is completely similar. So we leave it to the reader. This completes the proof of Theorem 3.2.

Finally we close this section with a remark.
Remark 3.3. Let $M$ be a positive quaternionic Kähler manifold manifold of dimension $4 m+4$ with an isometric $T^{m}$. If $4 m \geq 24$, then $m \geq[(m+1) / 2]+3$. Thus it follows from [8] that $M$ is isometric to $\mathbb{H} P^{m+1}$ or $G r_{2}\left(\mathbb{C}^{m+3}\right)$.

## 4 Proof of Theorem 1.2

In this section, we give a proof of Theorem 1.2. Essentially the proof is a direct corollary of Theorem 1.1. We use the mathematical induction on the dimension of a positive quaternionic Kähler manifold.

To do so, notice that the case of odd $m$ is already dealt with by the main result of the paper [9]. Thus it suffices to consider the case that $m$ is even. In the following proof, we continue to use the notations in Section 2. In particular, recall that $N_{1}$ is a fixed point component in $M$ of the induced $S^{1}$-action. The proof goes in two steps as follows.
Step 1: Assume first that $m=10$. This case has already been proved in Theorem 3.2.
Step 2: Next assume that the theorem holds for all dimensions less than or equal to $8 s_{0}\left(s_{0} \geq 5\right)$. For simplicity, let $l=2 s_{0}+2$. Let $M$ be a positive quaternionic Kähler $4 l$-manifold with $b_{4}(M)=1$ and an isometric $T^{\frac{l}{2}+1}$-action. We then want to show that $M$ is actually isometric to $\mathbb{H} P^{l}$.

Indeed, if $\operatorname{dim} N_{1}=4(l-1), N_{1}$ has codimension 4 in $M$. Since $l \geq 12$, $M$ is isometric to $\mathbb{H} P^{l}$ or $G r_{2}\left(\mathbb{C}^{l+2}\right)$ (cf. Theorem 1.2 in [5]). If $p=s_{0}+3$ and $4 p \leq \operatorname{dim}\left(N_{1}\right) \leq 4(l-2)$, it follows from the induction hypothesis that $N_{1}$ is isometric to a quaternionic projective space, since $b_{4}(M)=b_{4}\left(N_{1}\right)$ and $\operatorname{sym}-\operatorname{rank}\left(N_{1}\right) \geq l / 2$.

From $\pi_{2}(M)=\pi_{2}\left(N_{1}\right)=0$ (cf. Theorem 1.4), by the rigidity theorem of LeBrun and Salamon in [11], $M$ is isometric to $\mathbb{H} P^{l}$.

Now it remains to consider the case that $\operatorname{dim} N_{1} \leq 4\left(s_{0}+2\right)$. To do so, first note that $\operatorname{dim} N_{1} \geq 4(l / 2-1)=4 s_{0}$ (cf. Theorem B in [4]). Hence we need to consider the following two subcases:
(1) $4 s_{0} \leq \operatorname{dim} N_{1} \leq 4 s_{0}+4$.
(2) $\operatorname{dim} N_{1}=4 s_{0}+8$.

However, for the case (1), it is easy to see that the case that $N_{1}$ has dimension $4 s_{0}$ or $4 s_{0}+4$ with symmetry rank $s_{0}+1 \geq 5$ does not occur, since by Theorem 1.1 the dimension of $N_{1}$ should be greater than or equal to

$$
4\left(\frac{l}{2}+1\right)=2 l+4=4 s_{0}+8
$$

On the other hand, if $N_{1}$ has dimension $4 s_{0}+8$ with symmetry rank $s_{0}+1 \geq 6$ as in the case (2), we have $\pi_{2}\left(N_{1}\right)=0$ or $\mathbb{Z}$ by Remark 3.3. Thus we have $\pi_{2}(M)=0$ or $\mathbb{Z}$, thanks to Theorem 1.4 and so the relation $\pi_{2}\left(N_{1}\right)=\pi_{2}(M)$. By Theorem $1.3, M$ is isometric to $\mathbb{H} P^{l}$ or $G r_{2}\left(\mathbb{C}^{l+2}\right)$. Since $b_{4}(M)=1, M$ is isometric to $\mathbb{H} P^{l}$. This completes the proof of Theorem 1.2.

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