

Invitation to fixed-parameter algorithms

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joint work with

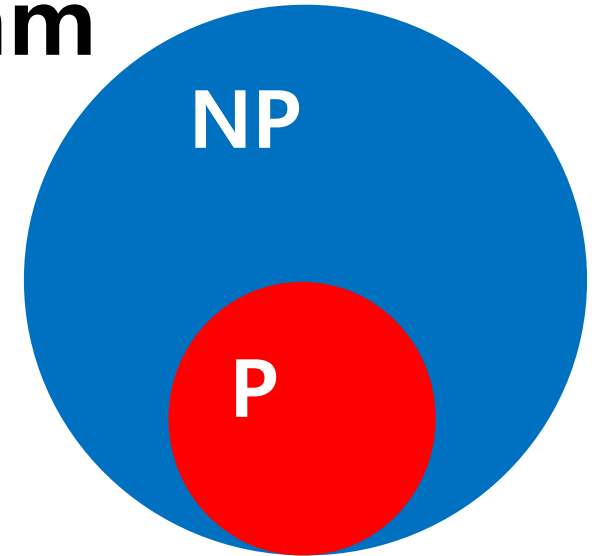
Sigve Hortemo Sæther and Jan Arne Telle (Univ. of Bergen, Norway),
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FWAC16, Yonsei University

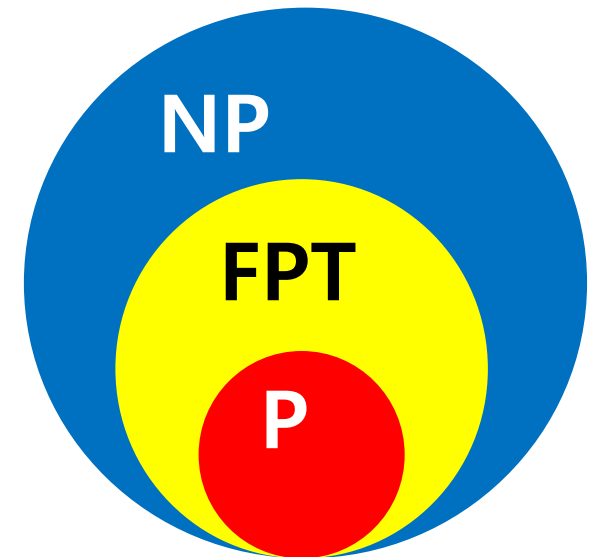
Nov. 11, 2016

Fixed-Parameter (Tractable) Algorithm

- **P = solve in time $\text{poly}(n)$**
- **NP = verify in time $\text{poly}(n)$**
- One of the Millennium Prize Problems
 $P \subset NP$ or $P=NP$



- **FPT = solve in time $f(k) \cdot \text{poly}(n)$**
- k is a parameter

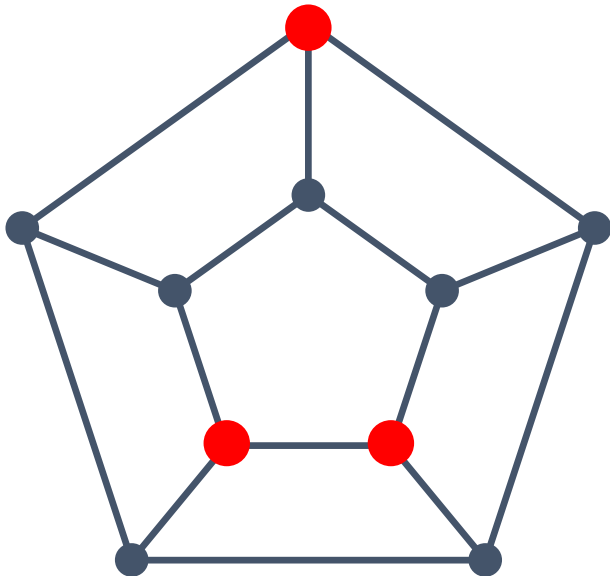


Examples

Dominating Set Problem

Input : a graph G

Question : what is the minimum size of a dominating set in G ?



- Dominating set = a set of vertices that dominates all vertices
- Dominating set problem is NP-hard

Examples

Dominating Set Problem

Input : a graph G

Question : what is the minimum size of a dominating set in G ?

Fixed-Parameter Algorithm for k -Dominating Set Problem

Input : a planar graph G , an integer k

Parameter : an integer k

Outputs : YES if a dominating set of size k exists
NO otherwise

Time : $2^{O(\sqrt{k})}n$

Examples

Planar Vertex Deletion

Input : a graph G , an integer k

Parameter : an integer k

Outputs : YES if a vertex subset X of size k
such that $G - X$ is planar

Eulerian Deletion

Input : a graph G , an integer k

Parameter : an integer k

Outputs : YES if an edge subset Y of size k
such that $G - Y$ is Eulerian

Examples

Minimum Dominating Set Problem

Input : a graph G having tree-width k

Parameter : an integer k

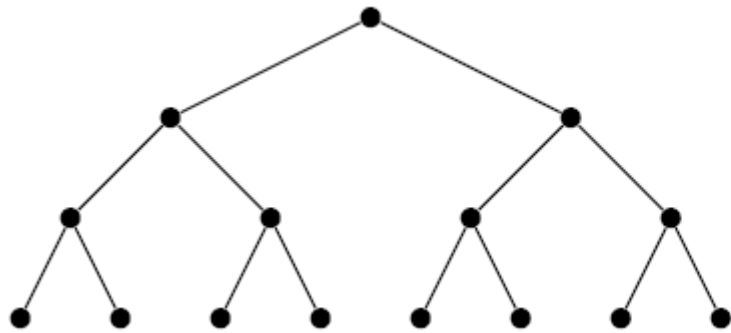
Outputs : the minimum size of a dominating set in G

Theorem (van Rooij, Bodlaender, Rossmanith 2009)

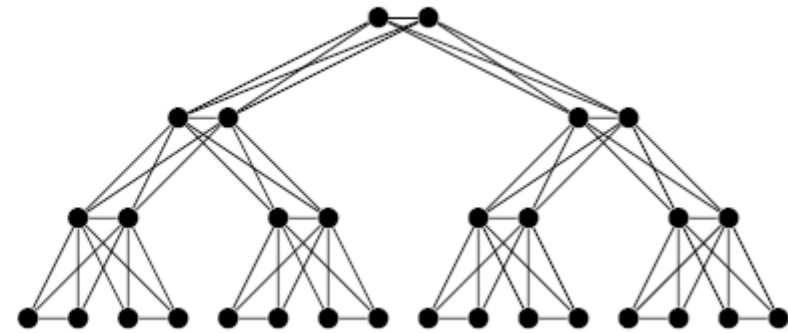
Minimum Dominating Set Problem can be solved in time $O(3^k) \cdot \text{poly}(n)$ if a graph has tree-width k .

Tree-width

- **tree-width** (Halin 1976, Robertson and Seymour 1984)
A measure of how “**tree-like**” the graph is.



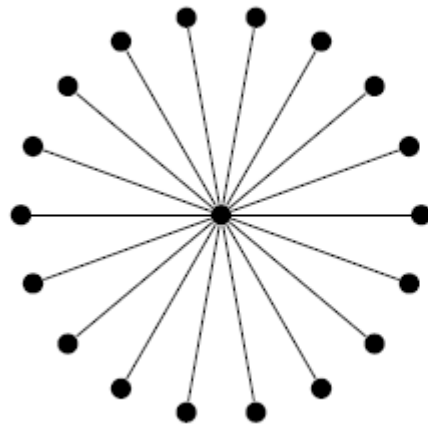
tree



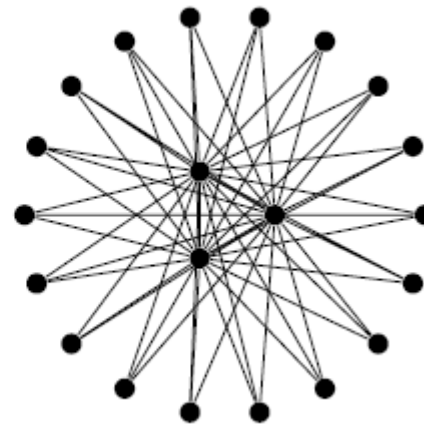
tree-like

Tree-width

- **tree-width** (Halin 1976, Robertson and Seymour 1984)
A measure of how “tree-like” the graph is.



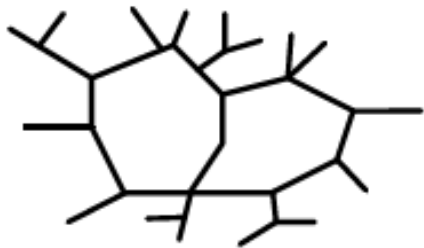
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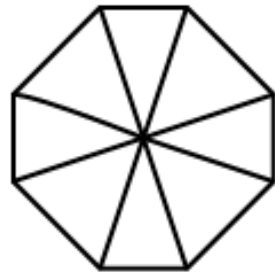
tree-like

Tree-width

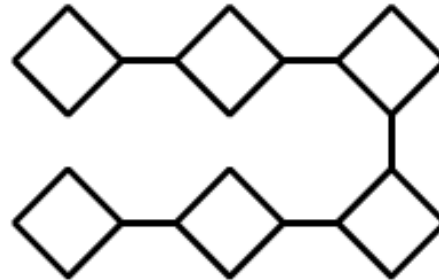
- **tree-width** (Halin 1976, Robertson and Seymour 1984)
A measure of how “**tree-like**” the graph is.



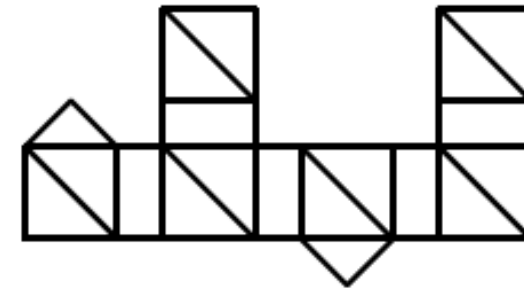
bad



bad



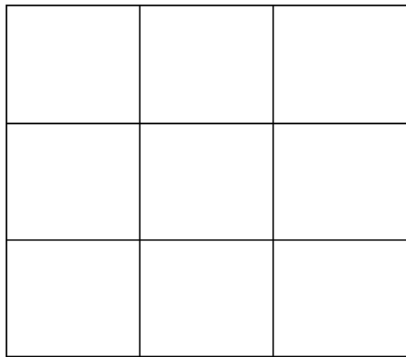
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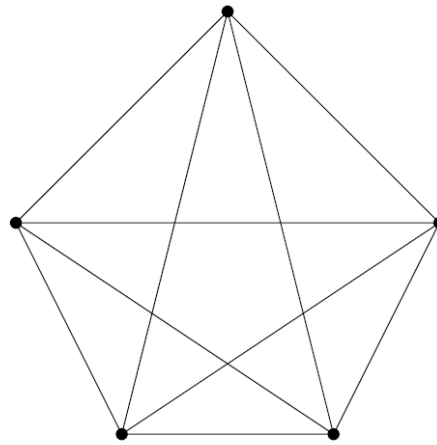
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Examples

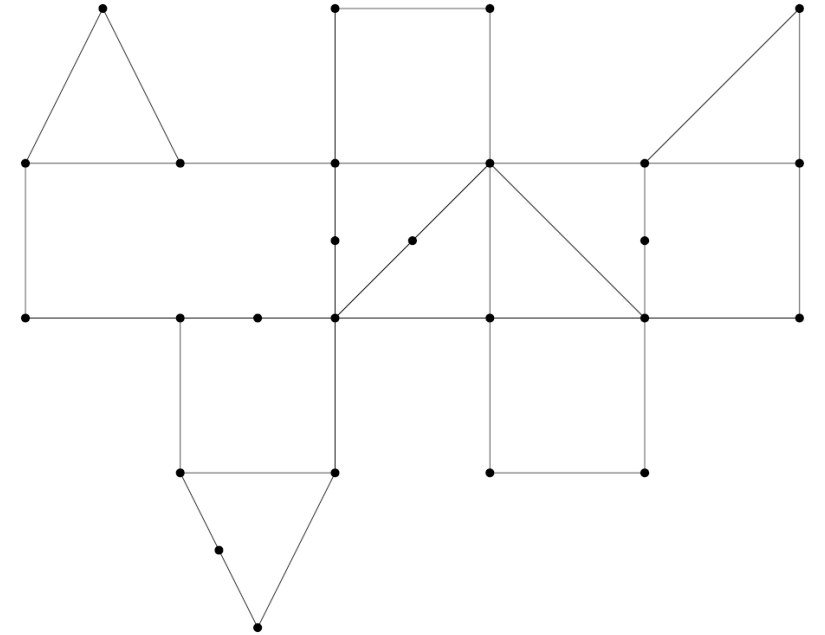
- tree-width $\leq 1 \Leftrightarrow$ a forest \Leftrightarrow no cycle
- tree-width $\leq 2 \Leftrightarrow$ a series-parallel graph
 \Leftrightarrow no K_4 minor
- The tree-width of a $k \times k$ grid is k .
- The tree-width of K_n is $n - 1$.



4 × 4 grid



K_5



Why treewidth?

Very general idea in science: large structures can be understood by breaking them into small pieces

In Computer Science: divide and conquer; dynamic programming

In Graph Algorithms: Exploiting small separators

Lower bounds for tree-width

Using tree-width

Theorem (van Rooij, Bodlaender, Rossmanith 2009)

Minimum Dominating Set Problem can be solved in time $O^*(3^t)$ when a graph has tree-width t .

Theorem (Lokshtanov, Marx, Saurabh 2011)

Minimum Dominating Set Problem cannot be solved in time $O^*((3 - \varepsilon)^t)$ where t is the tree-width of the given graph.

Maximum Matching width

Theorem (Vatshelle 2012)

For every graph G ,

$$mmw(G) \leq tw(G) + 1 \leq 3 mmw(G).$$

A graph G has bounded tree-width if and only if G has bounded maximum matching width.

Why Maximum Matching width?

Using maximum matching width

Theorem (J., Sæther, Telle IPEC2015)

Minimum Dominating Set Problem can be solved in time $O^*(8^m)$ when a graph has maximum matching width m .

Why Maximum Matching width?

Using tree-width: $O^*(3^t)$

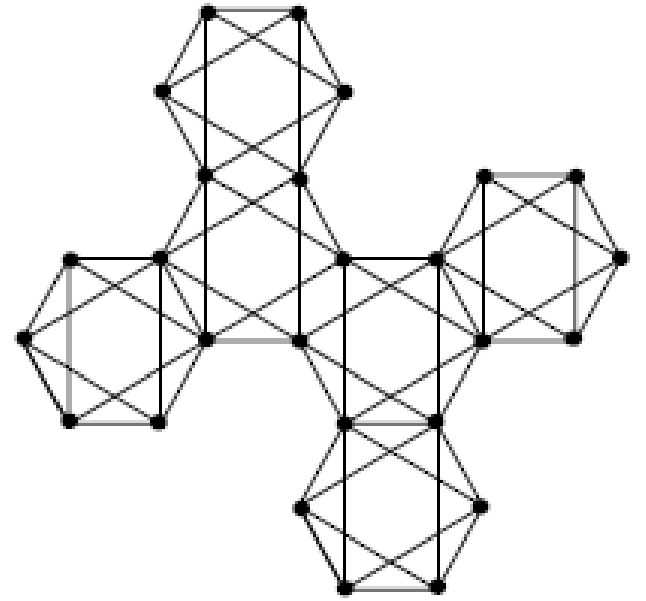
Using mm-width: $O^*(8^m)$

Our algorithm is **faster** when $8^m < 3^t$, that is,

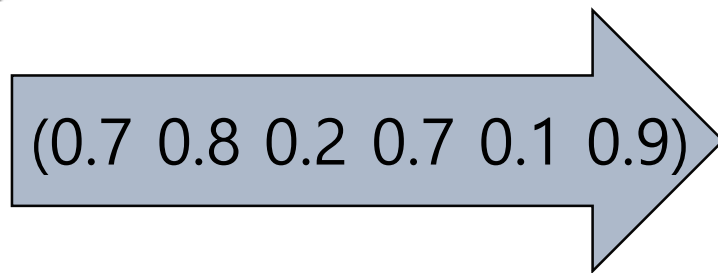
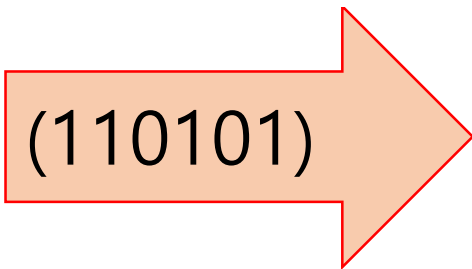
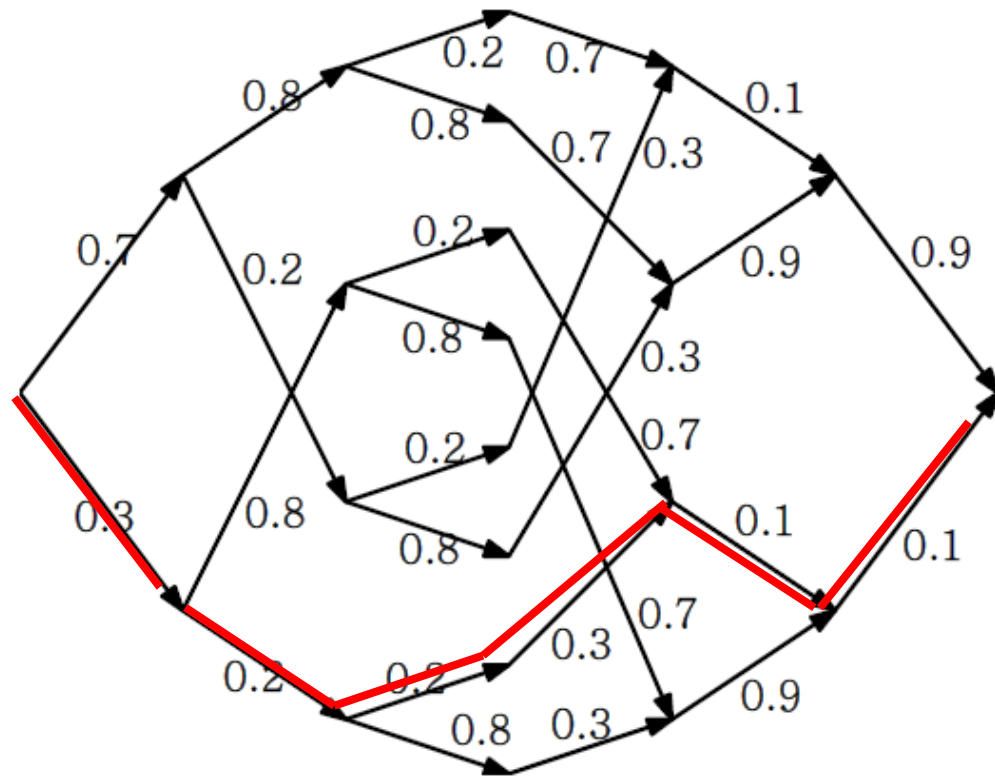
$$1.893 \text{ mmw}(G) < \text{tw}(G).$$

Note that for every graph G ,

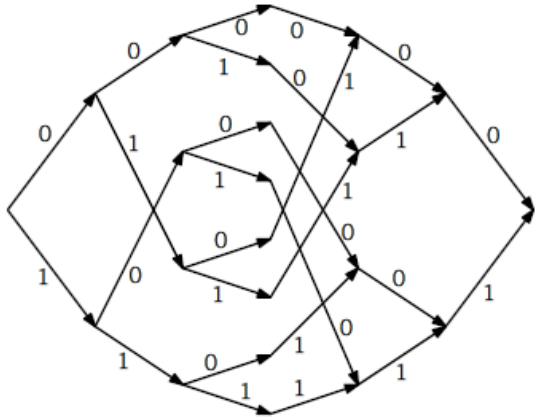
$$\text{mmw}(G) \leq \text{tw}(G) + 1 \leq 3 \text{ mmw}(G).$$



Decode using



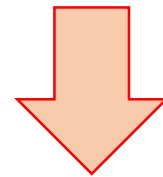
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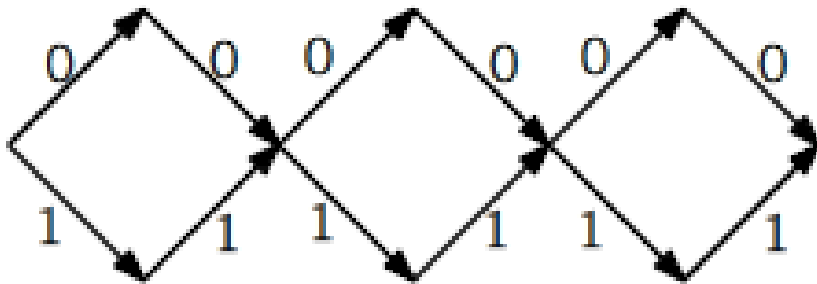
Want to make a better (thinner) trellis

Permute the columns of

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{pmatrix}$$



$$\pi = (1)(4)(5)(2,3,6)$$



$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

Our Results (J., Kim, Oum SODA2016)

Constructive algorithm for path-width of vectors (SODA2016)

Input : n vectors over F , an integer k

Output : a permutation v_1, v_2, \dots, v_n of n vectors satisfying that for all i ,

$$\dim\langle v_1, v_2, \dots, v_i \rangle \cap \langle v_{i+1}, v_{i+2}, \dots, v_n \rangle \leq k.$$

Time : FPT = $f(k) \cdot n^3$

$$\begin{array}{ccc|ccc} v_1 & v_2 & v_3 & v_4 & v_5 & v_6 \\ \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{array} \right) \end{array}$$

3

$$\begin{array}{ccc|ccc} v_1 & v_6 & v_2 & v_4 & v_5 & v_3 \\ \left(\begin{array}{ccc|ccc} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{array} \right) \end{array}$$

1

Actually, we proved a more general statement.

`vectors' \rightarrow `subspaces' (vector = 1-dimensional subspace)

Constructive algorithm for path-width of subspaces

Input : n subspaces over F , an integer k

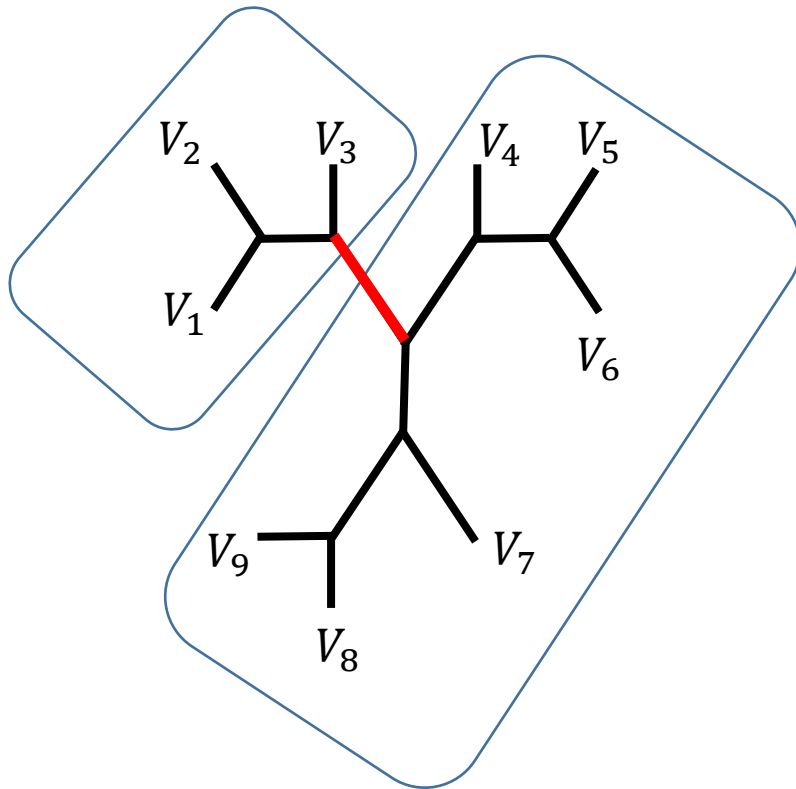
Output : a permutation V_1, V_2, \dots, V_n of n subspaces satisfying that for all i ,

$$\dim\langle V_1, V_2, \dots, V_i \rangle \cap \langle V_{i+1}, V_{i+2}, \dots, V_n \rangle \leq k.$$

Time : FPT = $f(k) \cdot n^3$

Theorem (J., Kim, Oum 2016+)

Roughly speaking, we can extend our algorithm to the **tree-version**.



$$\dim \langle V_1, V_2, V_3 \rangle \cap \langle V_4, V_5, \dots, V_9 \rangle \leq k$$

Thank you for listening

Proof ideas

1. Dynamic programming
2. Typical sequences
3. Subspace analysis (linear algebra)

Constructive algorithm for path-width of vectors (SODA16)

Input : n vectors over F , an integer k

Output : a permutation v_1, v_2, \dots, v_n of n vectors satisfying that for all i ,

$$\dim\langle v_1, v_2, \dots, v_i \rangle \cap \langle v_{i+1}, v_{i+2}, \dots, v_n \rangle \leq k.$$

Time : **FPT** = $f(k) \cdot n^3$